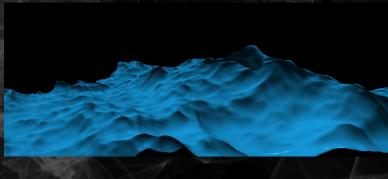
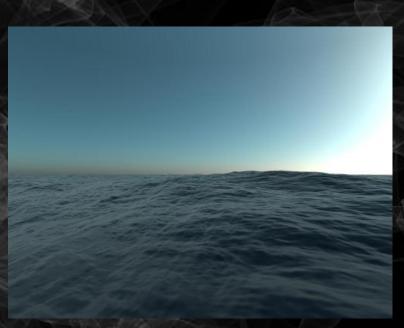


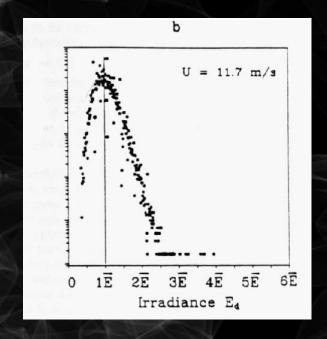




Objectives







- Oceanography concepts
- Random wave math
- Hints for realistic look
- Advanced things

$$h(x,z,t) = \int_{-\infty}^{\infty} dk_x \, dk_z \, \tilde{h}(\mathbf{k},t) \exp\left\{i(k_x x + k_z z)\right\}$$

$$\tilde{h}(\mathbf{k},t) = \tilde{h}_0(\mathbf{k}) \exp\left\{-i\omega_0(\mathbf{k})t\right\} + \tilde{h}_0^*(-\mathbf{k}) \exp\left\{i\omega_0(\mathbf{k})t\right\}$$





Contact Cast Away 13th Warrior

Deep Blue Sea

Virus

World Is Not Enough 13 Days

Fifth Element

Double Jeopardy

Devil's Advocate

20k Leagues Under the Sea





Navier-Stokes Fluid Dynamics

Force Equation

$$\frac{\partial \mathbf{u}(\mathbf{x},t)}{\partial t} + \mathbf{u}(\mathbf{x},t) \cdot \nabla \mathbf{u}(\mathbf{x},t) + \nabla p(\mathbf{x},t)/\rho = -g\hat{\mathbf{y}} + \mathbf{F}$$

Mass Conservation

$$\nabla \cdot \mathbf{u}(\mathbf{x}, t) = 0$$

Solve for functions of space and time:

- 3 velocity components
- pressure p
- \bullet density ρ distribution

Boundary conditions are important constraints

Very hard - Many scientitic careers built on this

Potential Flow

Special Substitution $\mathbf{u} = \nabla \phi(\mathbf{x},t)$

$$\mathbf{u} = \nabla \phi(\mathbf{x}, t)$$

Transforms the equations into

$$\frac{\partial \phi(\mathbf{x}, t)}{\partial t} + \frac{1}{2} |\nabla \phi(\mathbf{x}, t)|^2 + \frac{p(\mathbf{x}, t)}{\rho} + g\mathbf{x} \cdot \hat{\mathbf{y}} = 0$$

$$\nabla^2 \phi(\mathbf{x}, t) = 0$$

This problem is MUCH simpler computationally and mathematically.

Free Surface Potential Flow

In the water volume, mass conservation is enforced via

$$\phi(\mathbf{x}) = \int_{\partial V} dA' \left\{ \frac{\partial \phi(\mathbf{x}')}{\partial n'} G(\mathbf{x}, \mathbf{x}') - \phi(\mathbf{x}') \frac{\partial G(\mathbf{x}, \mathbf{x}')}{\partial n'} \right\}$$

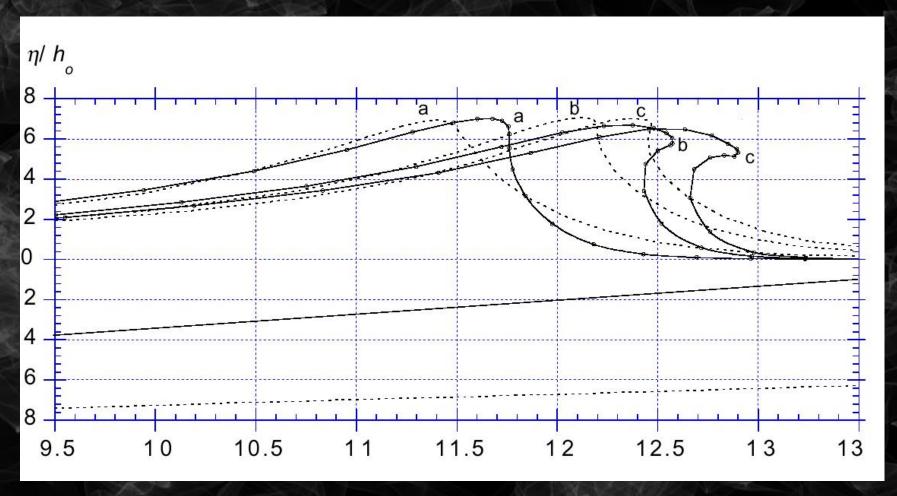
At points r on the surface

$$\frac{\partial \phi(\mathbf{r}, t)}{\partial t} + \frac{1}{2} |\nabla \phi(\mathbf{r}, t)|^2 + \frac{p(\mathbf{r}, t)}{\rho} + g\mathbf{r} \cdot \hat{\mathbf{y}} = 0$$

Dynamics of surface points:

$$\frac{d\mathbf{r}(t)}{dt} = \nabla \phi(\mathbf{r}, t)$$

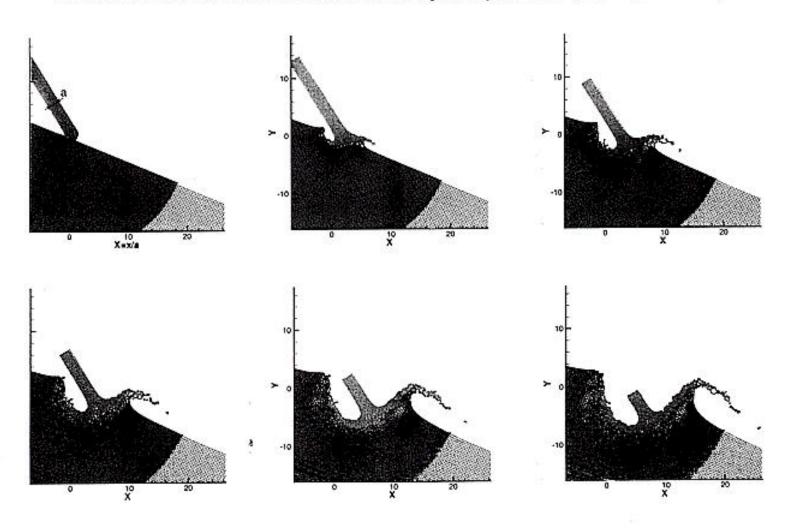
Numerical Wave Tank Simulation



Grilli, Guyenne, Dias (2000)

Plunging Break and Splash Simulation

Simulated Jet Impact on Wave Front.
Gridless Method: Smoothed Particle Hydrodynamics (100K particles).



Simplifying the Problem

Road to practicality - ocean surface:

- Simplify equations for relatively mild conditions
- Fill in gaps with oceanography.

Original dynamical equation at 3D points in volume

$$\frac{\partial \phi(\mathbf{r}, t)}{\partial t} + \frac{1}{2} |\nabla \phi(\mathbf{r}, t)|^2 + \frac{p(\mathbf{r}, t)}{\rho} + g\mathbf{r} \cdot \hat{\mathbf{y}} = 0$$

Equation at 2D points (x, z) on surface with height h

$$\frac{\partial \phi(x,z,t)}{\partial t} = -gh(x,z,t)$$

Simplifying the Problem: Mass Conservation

Vertical component of velocity

$$\frac{\partial h(x,z,t)}{\partial t} = \hat{\mathbf{y}} \cdot \nabla \phi(x,z,t)$$

Use mass conservation condition

$$\hat{\mathbf{y}} \cdot \nabla \phi(x, z, t) \sim \left(\sqrt{-\nabla_H^2}\right) \phi = \left(\sqrt{-\frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial z^2}}\right) \phi$$

Linearized Surface Waves

$$\frac{\partial h(x,z,t)}{\partial t} = \left(\sqrt{-\nabla_H^2}\right)\phi(x,z,t)$$

$$\frac{\partial \phi(x,z,t)}{\partial t} = -gh(x,z,t)$$

General solution easily computed in terms of Fourier Transforms

Solution for Linearized Surface Waves

General solution in terms of Fourier Transform

$$h(x,z,t) = \int_{-\infty}^{\infty} dk_x \, dk_z \, \tilde{h}(\mathbf{k},t) \, \exp\left\{i(k_x x + k_z z)\right\}$$

with the amplitude depending on the dispersion relationship

$$\omega_0(\mathbf{k}) = \sqrt{g \, |\mathbf{k}|}$$

$$\tilde{h}(\mathbf{k},t) = \tilde{h}_0(\mathbf{k}) \exp\left\{-i\omega_0(\mathbf{k})t\right\} + \tilde{h}_0^*(-\mathbf{k}) \exp\left\{i\omega_0(\mathbf{k})t\right\}$$

The complex amplitude $\tilde{h}_0(\mathbf{k})$ is arbitrary.

Oceanography

- Think of the heights of the waves as a kind of random process
- Decades of detailed measurements support a statistical description of ocean waves.
- The wave height has a spectrum

$$\left\langle \left| \tilde{h}_0(\mathbf{k}) \right|^2 \right\rangle = P_0(\mathbf{k})$$

ullet Oceanographic models tie P_0 to environmental parameters like wind velocity, temperature, salinity, etc.

Models of Spectrum

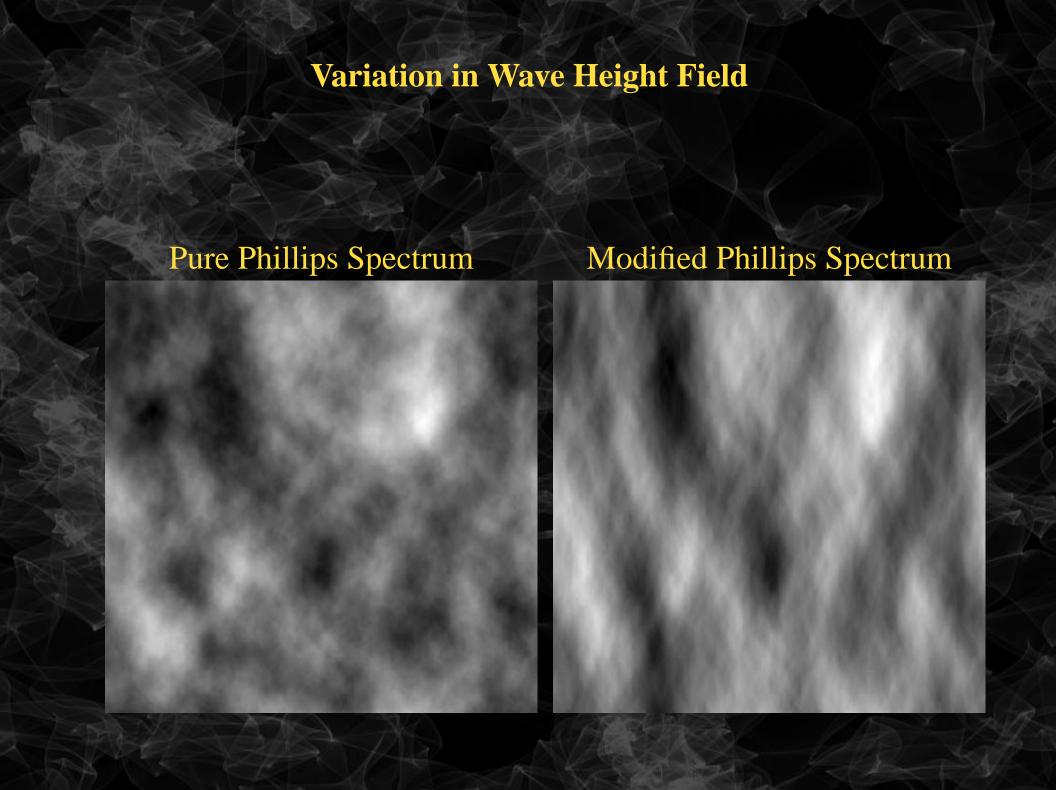
- Wind speed V
- ullet Wind direction vector $\hat{\mathbf{V}}$ (horizontal only)
- Length scale of biggest waves $L = V^2/g$ (g=gravitational constant)

Phillips Spectrum

$$P_0(\mathbf{k}) = \left| \hat{\mathbf{k}} \cdot \hat{\mathbf{V}} \right|^2 \frac{\exp(-1/k^2 L^2)}{k^4}$$

JONSWAP Frequency Spectrum

$$P_0(\omega) = \frac{\exp\left\{-\frac{5}{4}\left(\frac{\omega}{\Omega}\right)^{-4} + e^{-(\omega-\Omega)^2/2(\sigma\Omega)^2}\ln\gamma\right\}}{\omega^5}$$



Simulation of a Random Surface

Generate a set of "random" amplitudes on a grid

$$\tilde{h}_0(\mathbf{k}) = \xi e^{i\theta} \sqrt{P_0(\mathbf{k})}$$

 ξ = Gaussian random number, mean 0 & std dev 1 θ = Uniform random number [0,2 π].

$$k_x = \frac{2\pi}{\Delta x} \frac{n}{N} \ (n = -N/2, \dots, (N-1)/2)$$

$$k_z = \frac{2\pi}{\Delta z} \frac{m}{M} \ (m = -M/2, \dots, (M-1)/2)$$

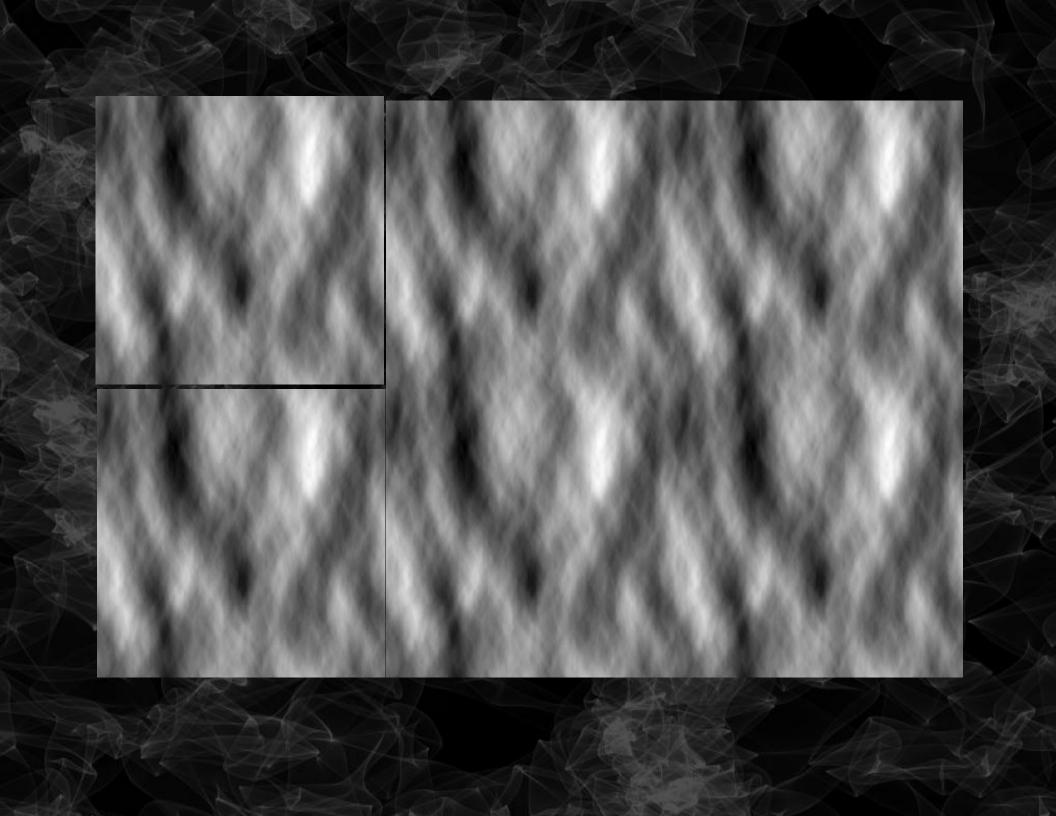
FFT of Random Amplitudes

Use the Fast Fourier Transform (FFT) on the amplitudes to obtain the wave height realization h(x,z,t)

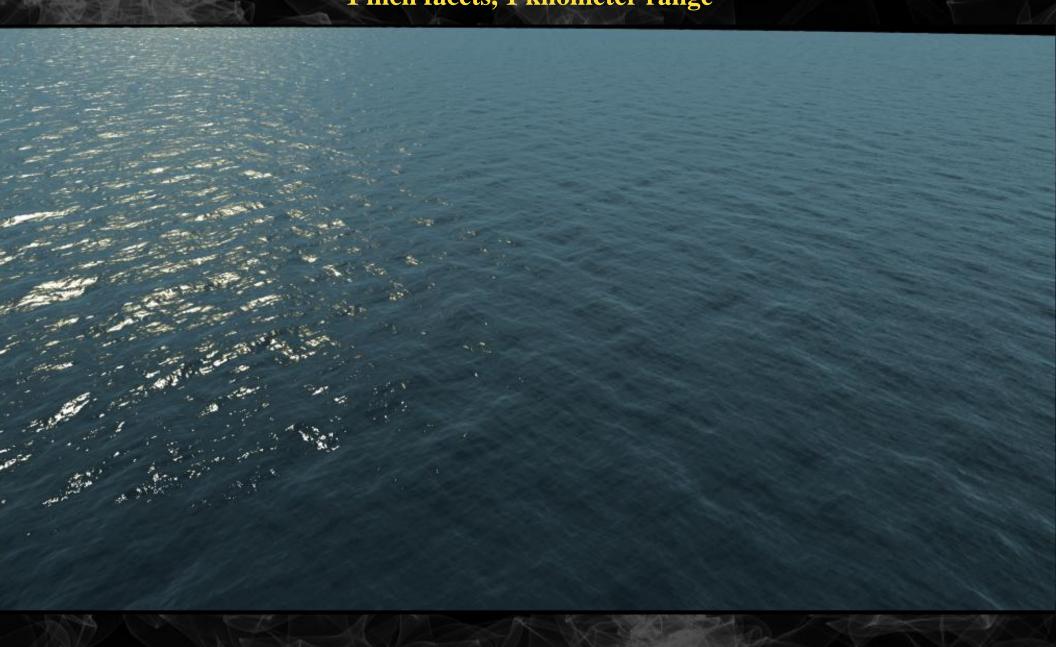
Wave height realization exists on a regular, periodic grid of points.

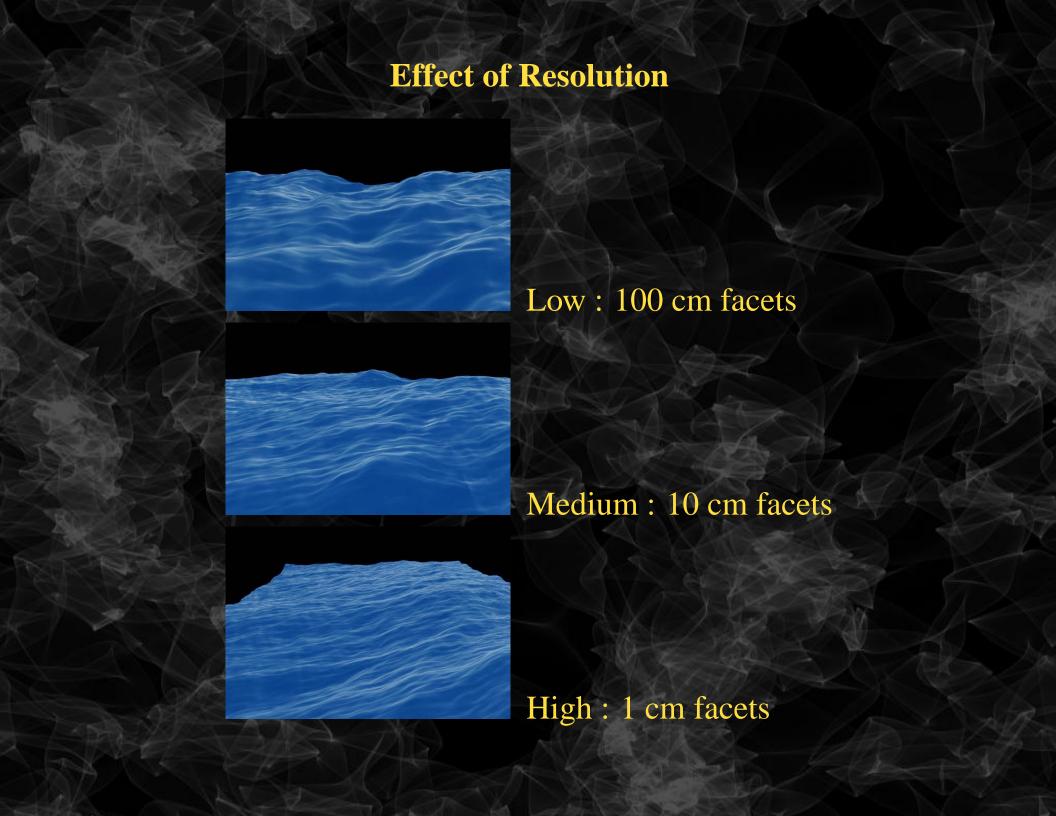
$$x = n\Delta x$$
 $(n = -N/2, ..., (N-1)/2)$
 $z = m\Delta z$ $(m = -M/2, ..., (M-1)/2)$

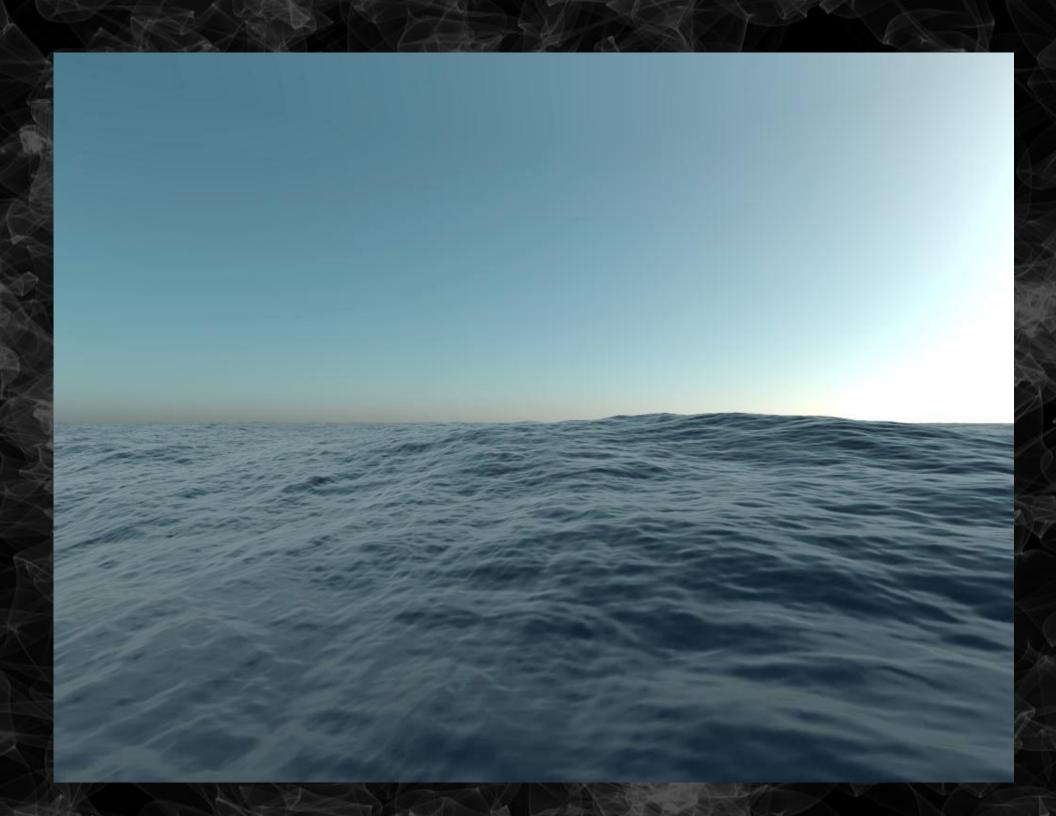
The realization tiles seamlessly. This can sometimes show up as repetitive waves in a render.



High Resolution Rendering Sky reflection, upwelling light, sun glitter 1 inch facets, 1 kilometer range

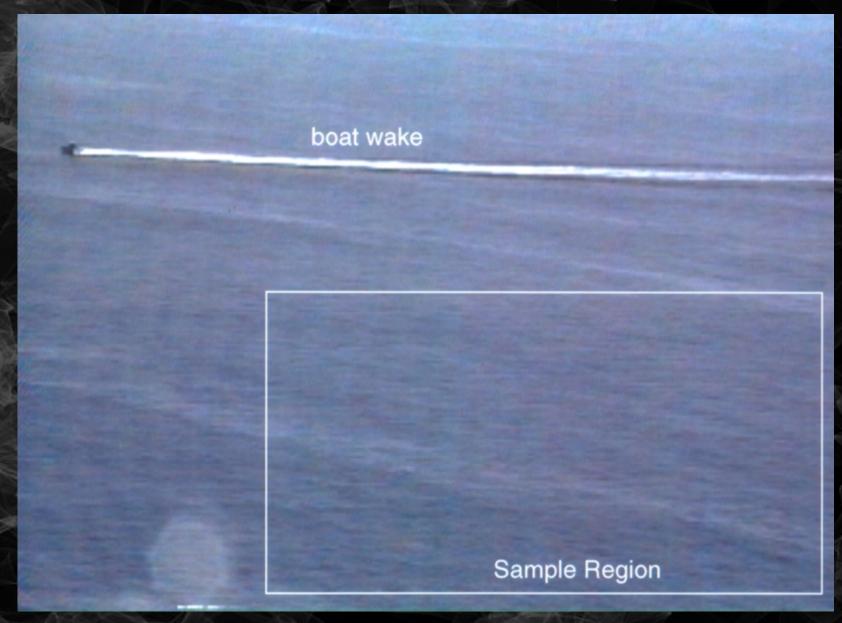








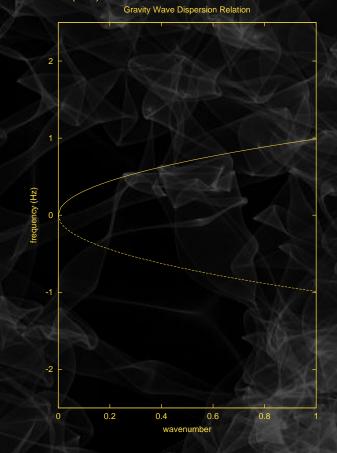
Simple Demonstration of Dispersion



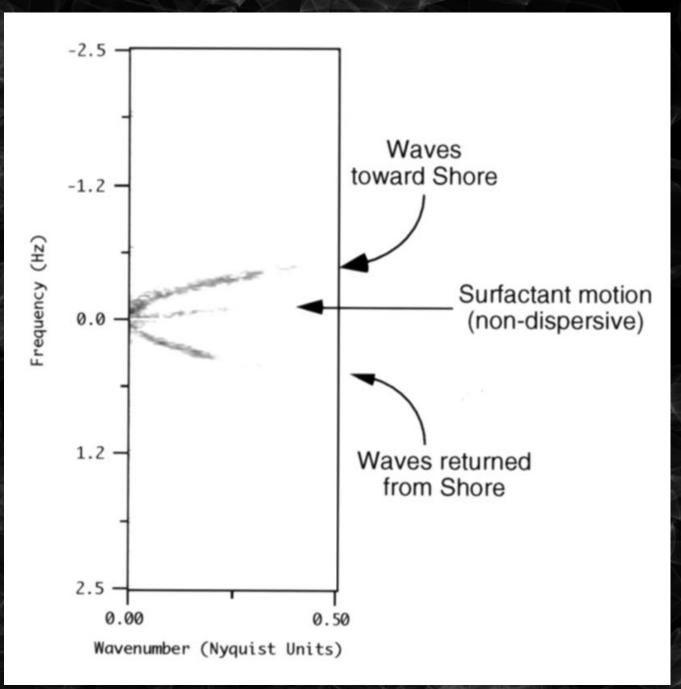
256 frames, 256×128 region

Data Processing

- Fourier transform in both time and space: $\tilde{h}(\mathbf{k},\omega)$
- Form Power Spectral Density $P(\mathbf{k}, \omega) = \left\langle \left| \tilde{h}(\mathbf{k}, \omega) \right|^2 \right\rangle$
- If the waves follow dispersion relationship, then P is strongest at frequencies $\omega = \omega(k)$.



Processing Results



Looping in Time – Continuous Loops

- Continuous loops can't be made because dispersion doesn't have a fundamental frequency.
- Loops can be made by modifying the dispersion relationship.

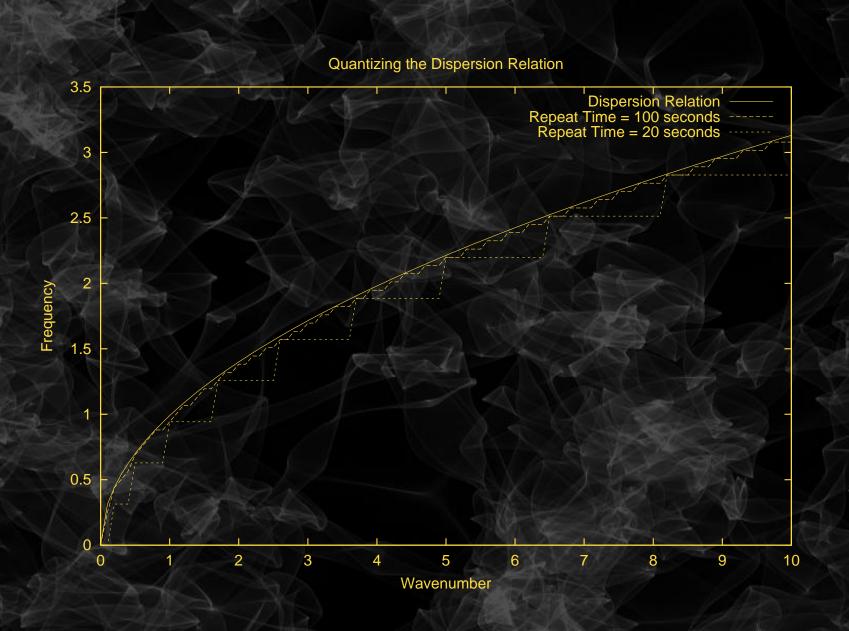
Repeat time

 \overline{T}

Fundamental Frequency $\omega_0 = \frac{2\pi}{T}$

New dispersion relation $\tilde{\omega} = \operatorname{integer}\left(\frac{\omega(k)}{\omega_0}\right) \ \omega_0$

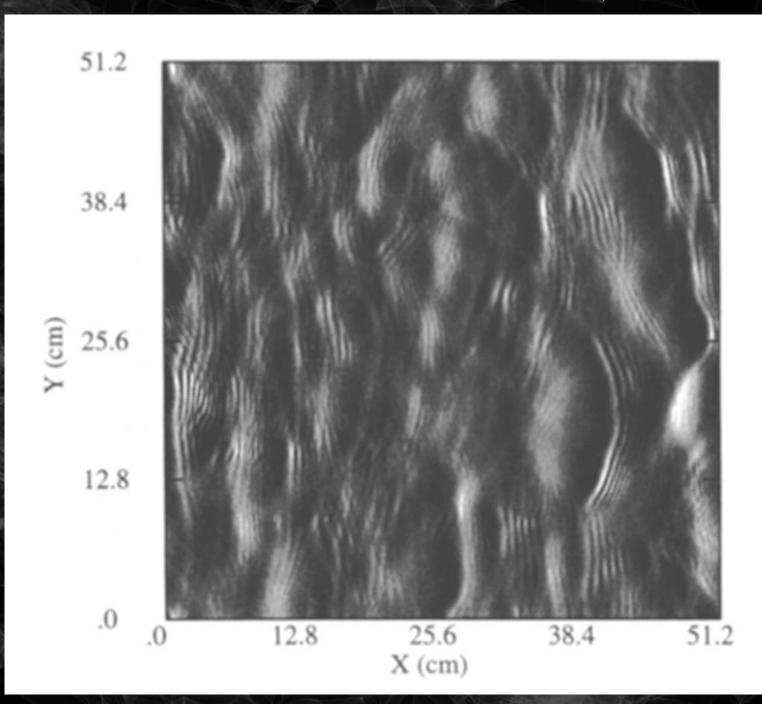
Quantized Dispersion Relation



Hamiltonian Approach for Surface Waves Miles, Milder, Henyey, ...

- If a crazy-looking surface operator like $\sqrt{-\nabla_H^2}$ is ok, the exact problem can be recast as a canonical problem with momentum ϕ and coordinate h in 2D.
- Milder has demonstrated numerically:
 - The onset of wave breaking
 - Accurate capillary wave interaction
- Henyey et al. introduced Canonical Lie Transformations:
 - Start with the solution of the linearized problem (ϕ_0,h_0)
 - Introduce a continuous set of transformed fields (ϕ_q, h_q)
 - The exact solution for surface waves is for q=1.

Surface Wave Simulation (Milder, 1990)



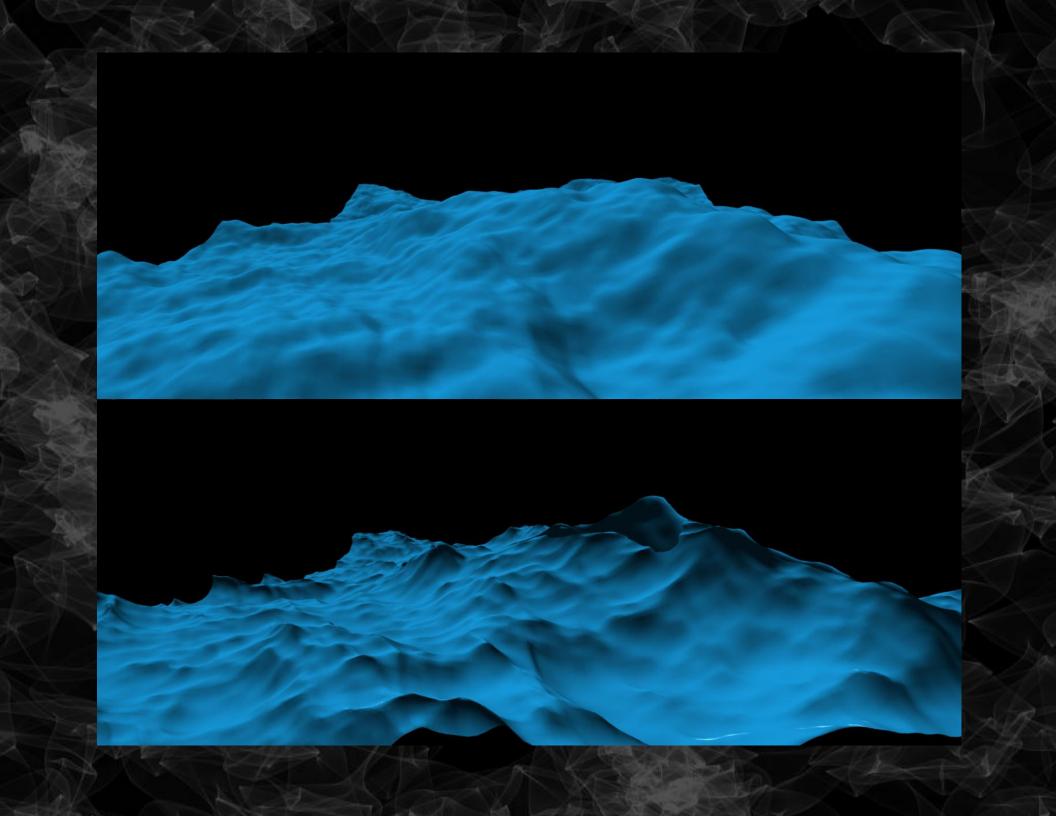
Choppy, Near-Breaking Waves

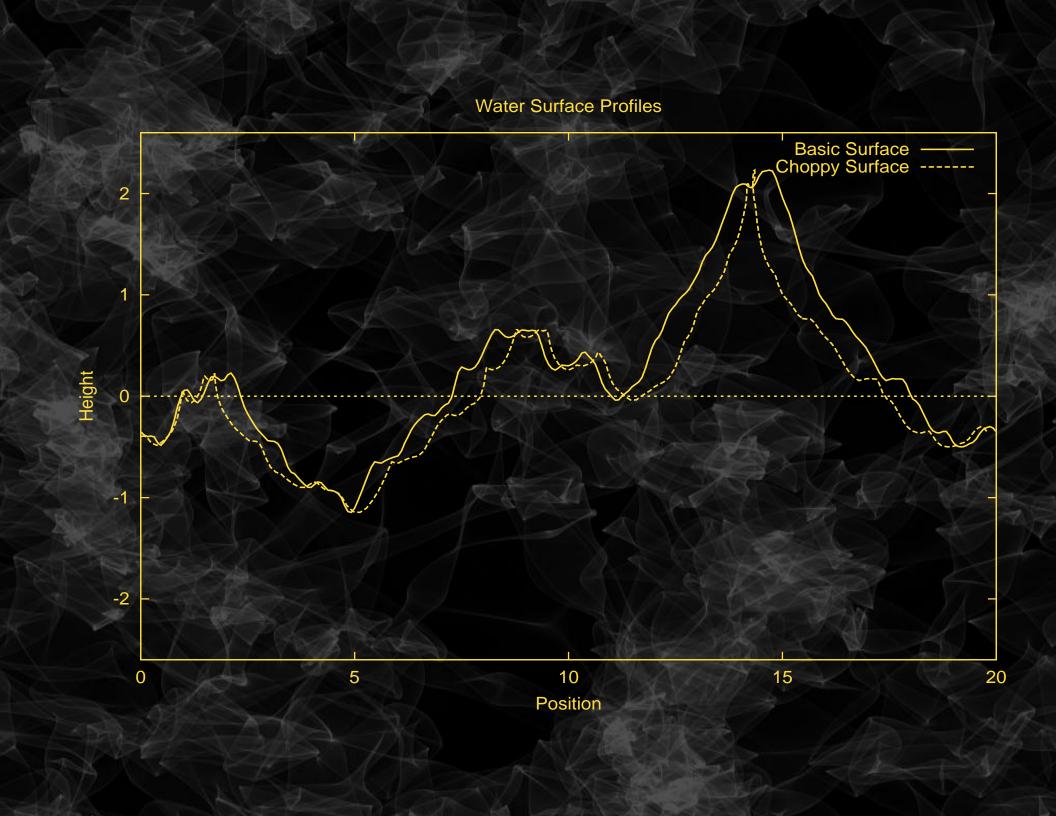
Horizontal velocity becomes important for distorting wave.

Wave at x morphs horizontally to the position $\mathbf{x} + \mathbf{D}(\mathbf{x}, t)$

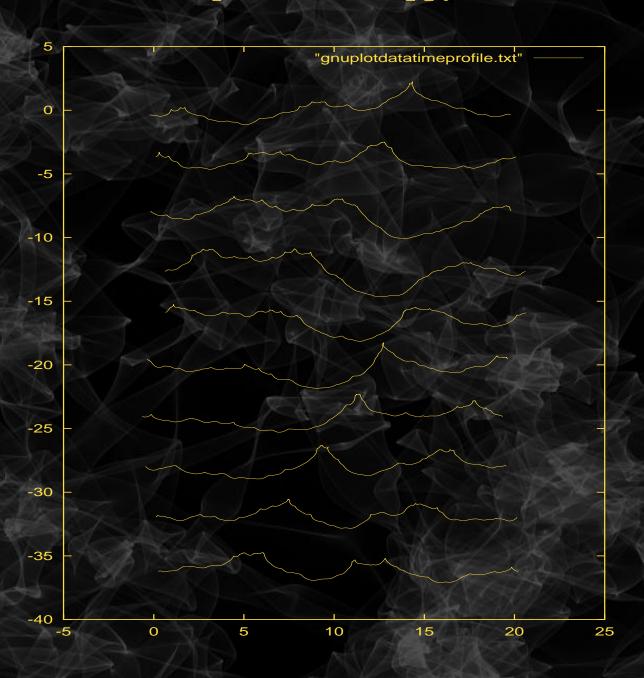
$$\mathbf{D}(\mathbf{x},t) = -\lambda \int d^2k \, \frac{i\mathbf{k}}{|\mathbf{k}|} \tilde{h}(\mathbf{k},t) \, \exp\left\{i(k_x x + k_z z)\right\}$$

The factor λ allows artistic control over the magnitude of the morph.





Time Sequence of Choppy Waves



Choppy Waves: Detecting Overlap

$$\mathbf{x} \to \mathbf{X}(\mathbf{x}, t) = \mathbf{x} + \mathbf{D}(\mathbf{x}, t)$$

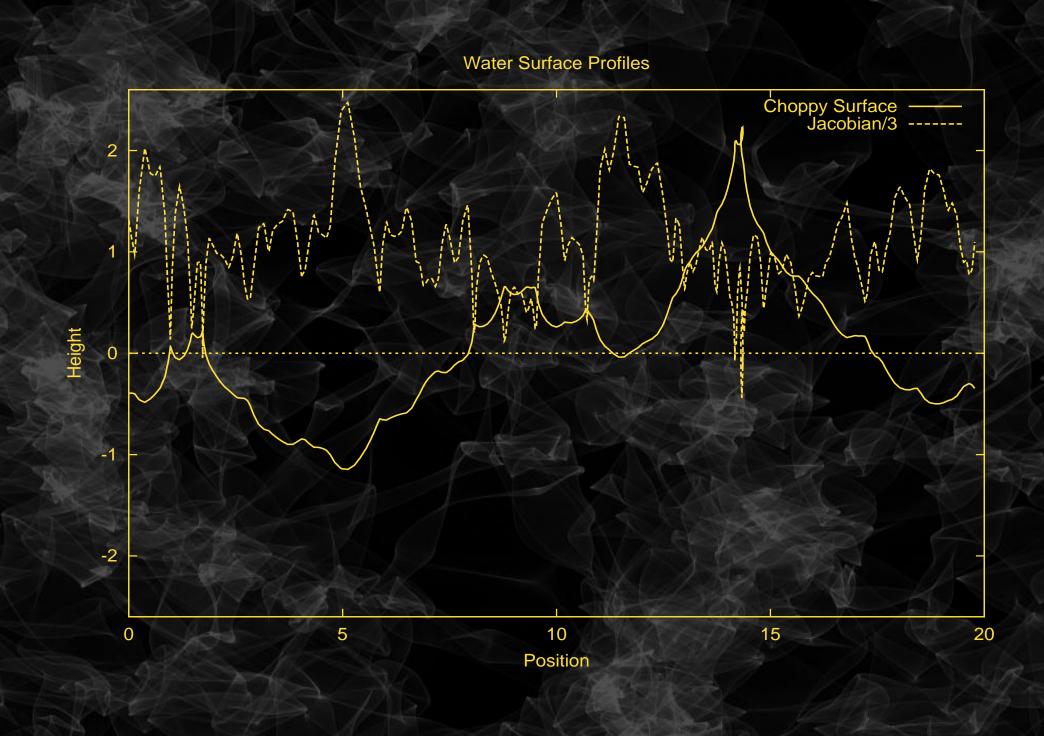
is unique and invertible as long as the surface does not intersect itself.

When the mapping intersects itself, it is not unique. The quantitative measure of this is the *Jacobian* matrix

$$J(\mathbf{x},t) = \begin{bmatrix} \partial \mathbf{X}_x / \partial x & \partial \mathbf{X}_x / \partial z \\ \partial \mathbf{X}_z / \partial x & \partial \mathbf{X}_z / \partial z \end{bmatrix}$$

The signal that the surface intersects itself is

$$\det(J) \leq 0$$



Learning More About Overlap

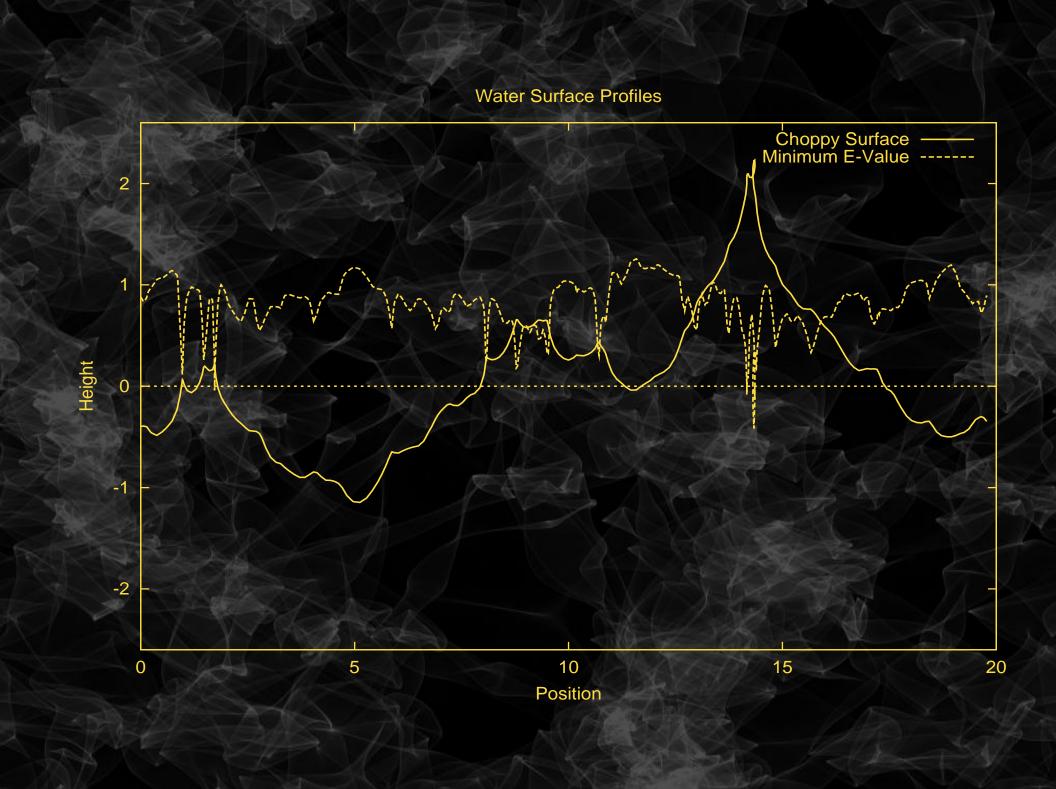
Two eigenvalues, $J_{-} \leq J_{+}$, and eigenvectors $\hat{\mathbf{e}}_{-}$, $\hat{\mathbf{e}}_{+}$

$$J = J_{-}\hat{\mathbf{e}}_{-}\hat{\mathbf{e}}_{-} + J_{+}\hat{\mathbf{e}}_{+}\hat{\mathbf{e}}_{+}$$

$$\det(J) = J_- J_+$$

For no chop, $J_- = J_+ = 1$. As the displacement magnitude increases, J_+ stays positive while J_- becomes negative at the location of overlap.

At overlap, $J_{-} < 0$, the alignment of the overlap is parallel to the eigenvalue $\hat{\mathbf{e}}_{-}$.



Simple Spray Algorithm

- Pick a point on the surface at random
- ullet Emit a spray particle if $J_- < J_T$ threshold
- Particle initial direction (\hat{n} = surface normal)

$$\hat{\mathbf{v}} = \frac{(J_T - J_-)\hat{\mathbf{e}}_- + \hat{\mathbf{n}}}{\sqrt{1 + (J_T - J_-)^2}}$$

- ullet Particle initial speed from a half-gaussian distribution with mean proportional to J_T-J_- .
- Simple particle dynamics: gravity and wind drag



Summary

- FFT-based random ocean surfaces are fast to build, realistic, and flexible.
- Based on a mixture of theory and experimental phenomenology.
- Used alot in professional productions.
- Real-time capable for games
- Lots of room for more complex behaviors.

Latest version of course notes and slides:

http://home1.gte.net/tssndrf/index.html

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