

Introduction to Computer Graphics



Marie-Paule Cani : Cours

Estelle Duveau : CTD OpenGL

Computer Graphics

- **3D animation**
 - « Disney Effects »
(Luxo Jr (1986)
Pixar animation studios
Director: John Lasseter)



Computer Graphics

- **Special effects**
 - Seam-less mix of real & virtual



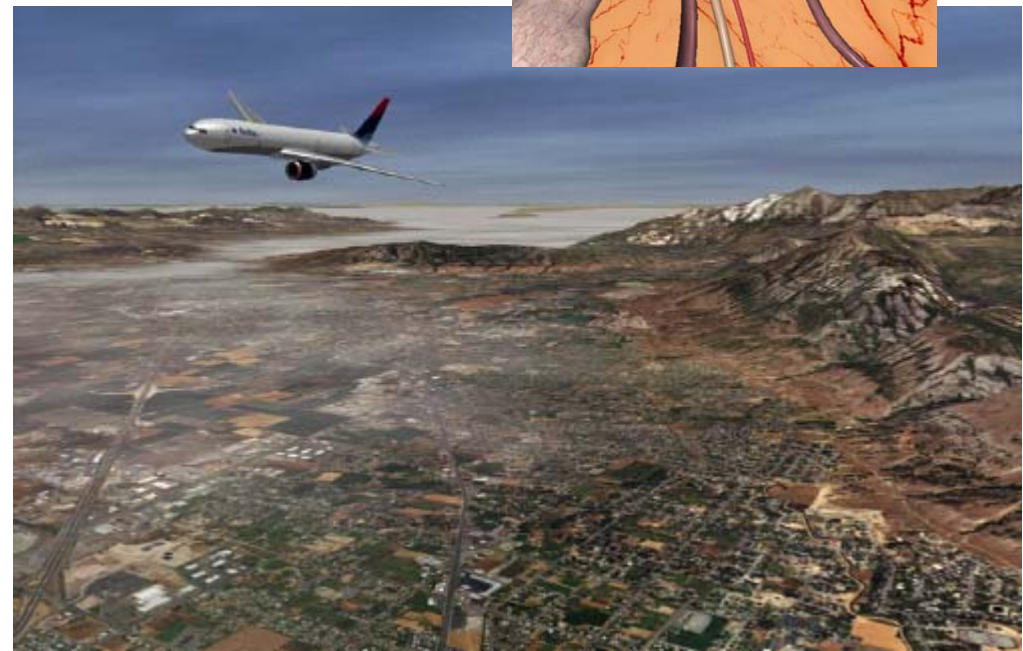
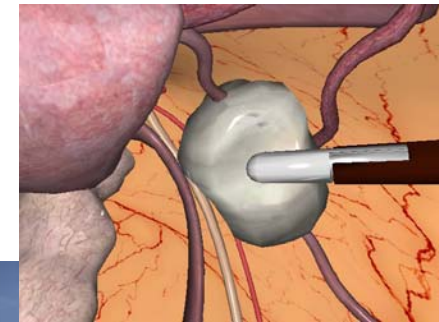
Computer Graphics

- Games
 - Immersion through interaction



Computer Graphics

- Simulation : « serious games »
 - Predictability & interaction



Computer Graphics

- Computer Aided Design (CAD)
 - Virtual prototypes



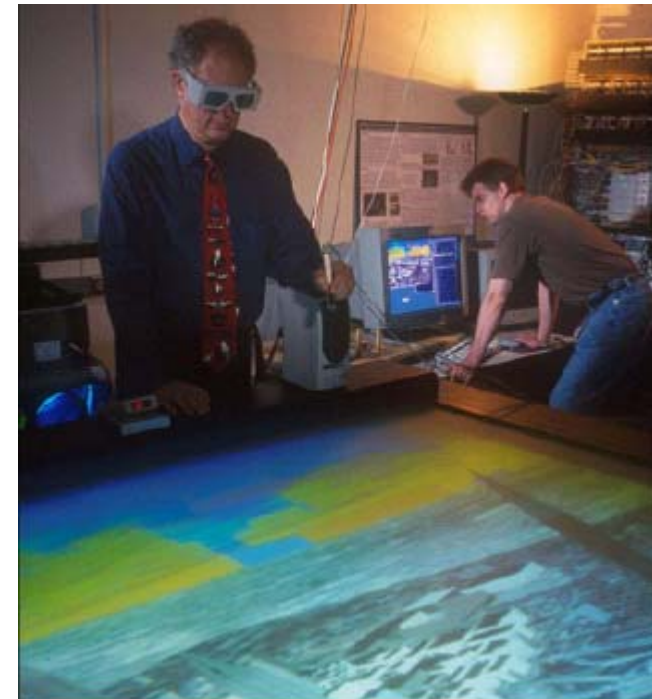
Computer Graphics

- **Architecture**
 - Real-time exploration



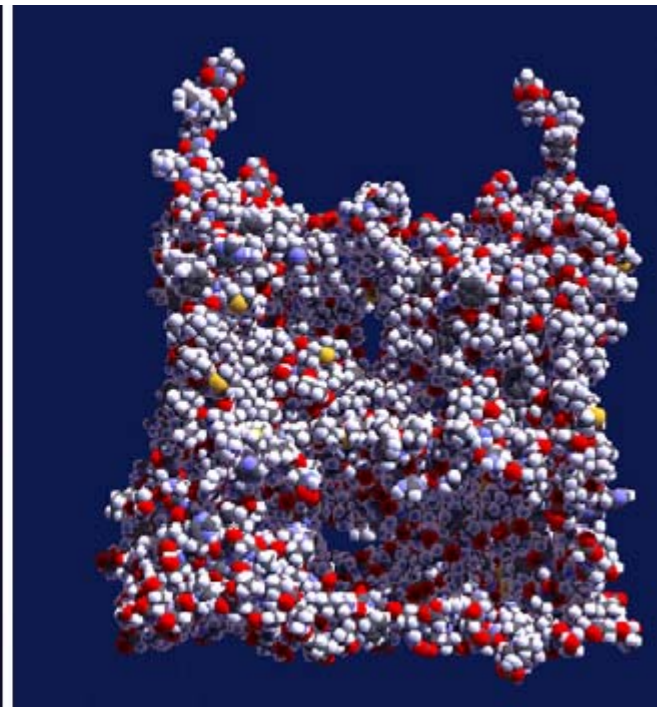
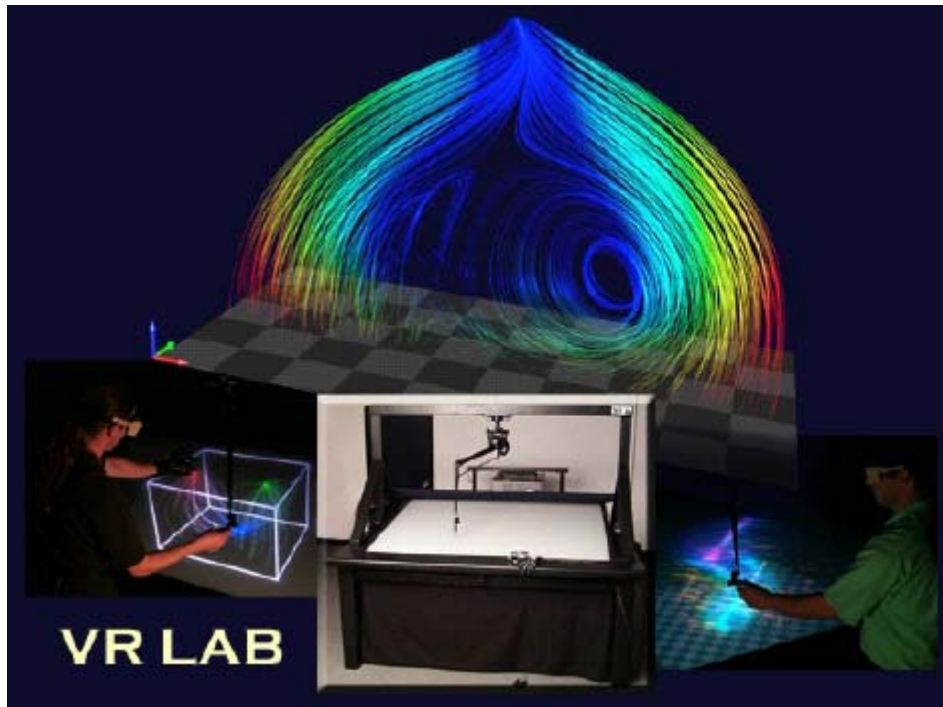
Computer Graphics

- Virtual reality
 - Multi-sensorial immersion
- Augmented reality



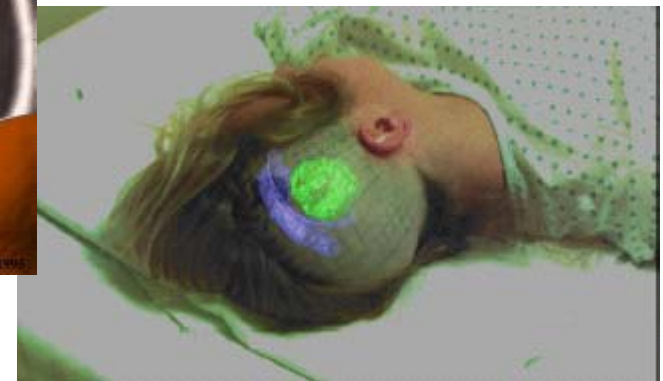
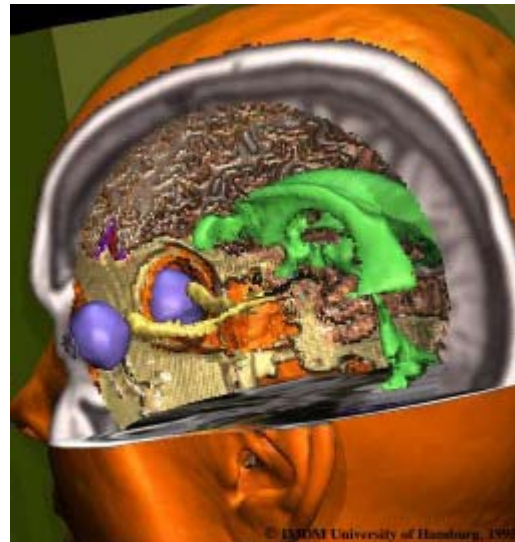
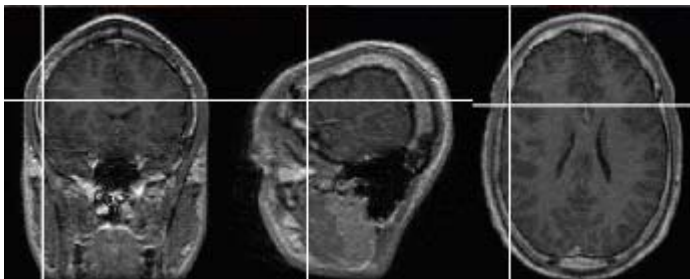
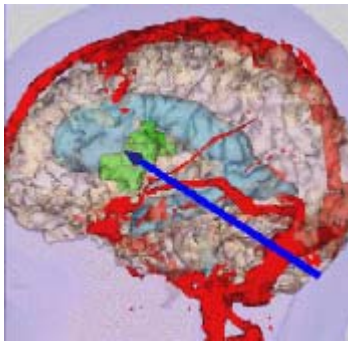
Computer Graphics

- **Visualization**
 - Visual exploration of results, interaction

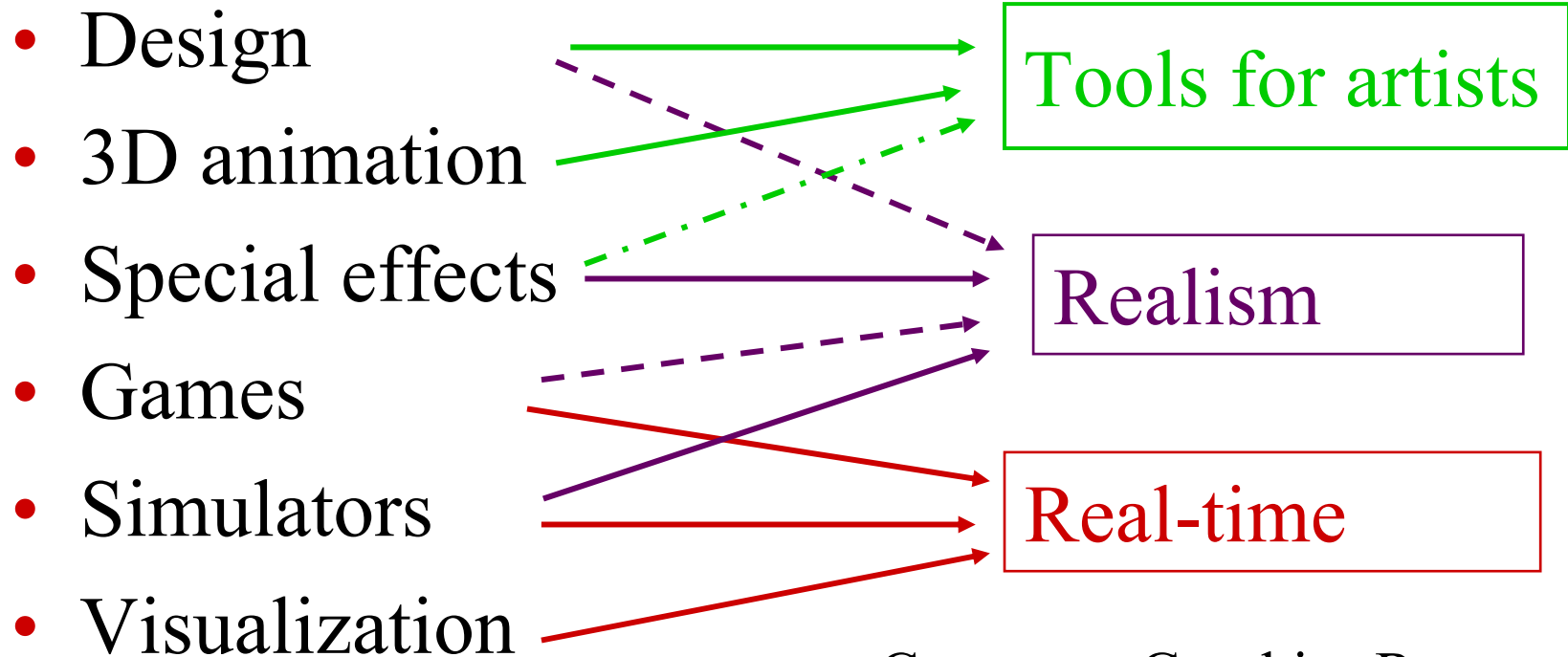


Computer Graphics

- Medical imaging
 - Understanding, planning, on-line monitoring



Computer Graphics



Computer Graphics Research

What you will learn

- Overview of Computer Graphics (including vocabulary)
 - Modeling : create 3D geometry
 - Animation : move & deform
 - Rendering : 3D scene → image
- How basic techniques work
- Practice with OpenGL (C++)
- Introduction to research : case studies
 - Choose/combine/extend existing techniques to solve a problem



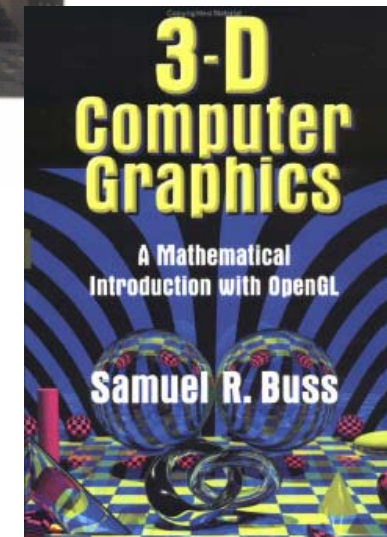
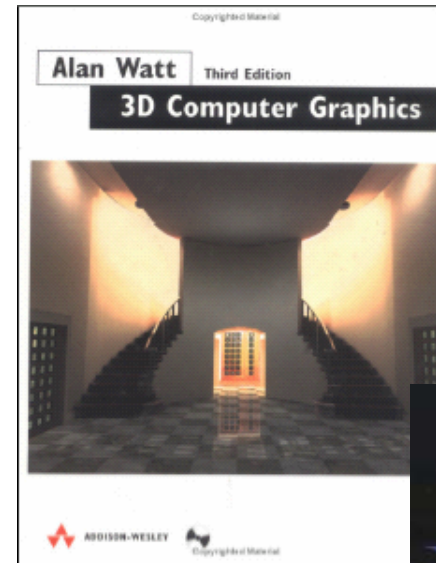
What you will not learn

- Advanced techniques in detail
- Programming the Graphics Hardware (GPU)
- Artistic skills
- Game design
- Software packages
(CAD-CAM, 3D Studio Max, Maya, Photoshop, etc)

Following up: **MOSIG M2 “GVR” & ENSIMAG “IRV”**

Text books

- No book **required**
- References
 - *3D Computer Graphics*
Alan H. Watt
 - *3D Computer Graphics: A Mathematical Introduction with OpenGL* (2003) by Buss.



Course schedule (3h a week, A009 or ARV)

Marie-Paule Cani & Estelle Duveau

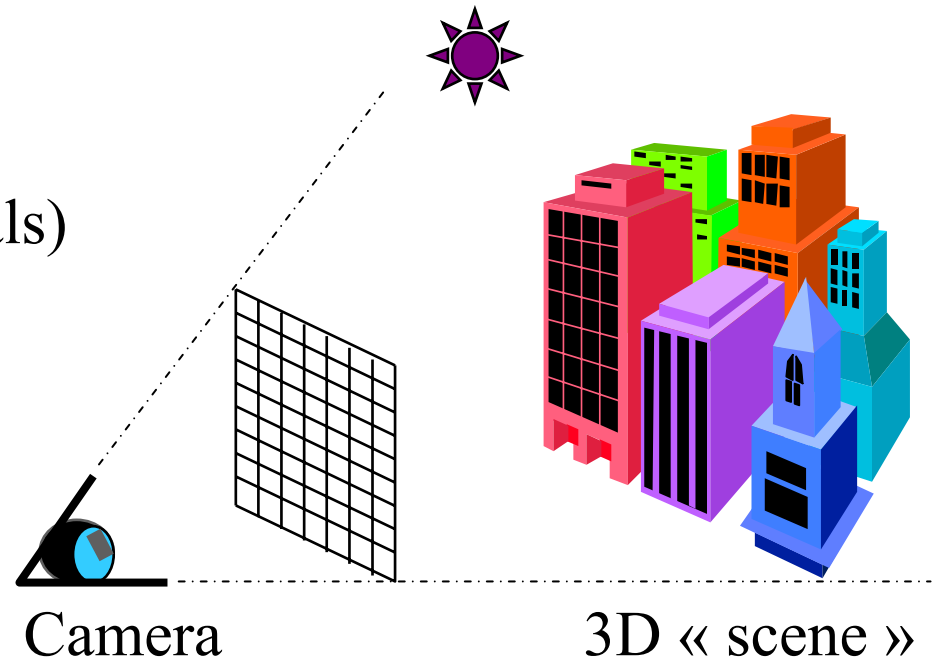
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- 04/02 Introduction + Projective rendering: graphics pipeline, shading
 - 11/02 Parametric modeling : representations + design tools
 - 25/02 **Introduction to OpenGL: C + TD**
 - 04/03 Implicit surfaces 1 + **CTD matrices & hierarchies**
 - 11/03 Implicit surfaces 2 + **C OpenGL lighting, materials**
 - 18/03 Textures, aliasing + **TD OpenGL lighting, materials**
 - 25/03 **Textures in OpenGL: C + TD**
 - 01/04 Procedural & kinematic animation + **TD procedural anim**
 - 08/04 Physics: particle systems + **TD physics 1**
 - 22/04 Physics: collisions, control + **TD physics 2**
 - 29/04 Animating complex objects + Realistic rendering
 - 06/05 Talks: results of cases studies

Basic, real-time display?

Projective rendering

Done by the graphics hardware via OpenGL or DirectX

- Input: **Scene**
 - 3D models (Faces & normals)
- Goal
 - Image from camera
Made of **pixels**



Basic, real-time display?

Projective rendering

2 ingredients:

Graphics pipeline

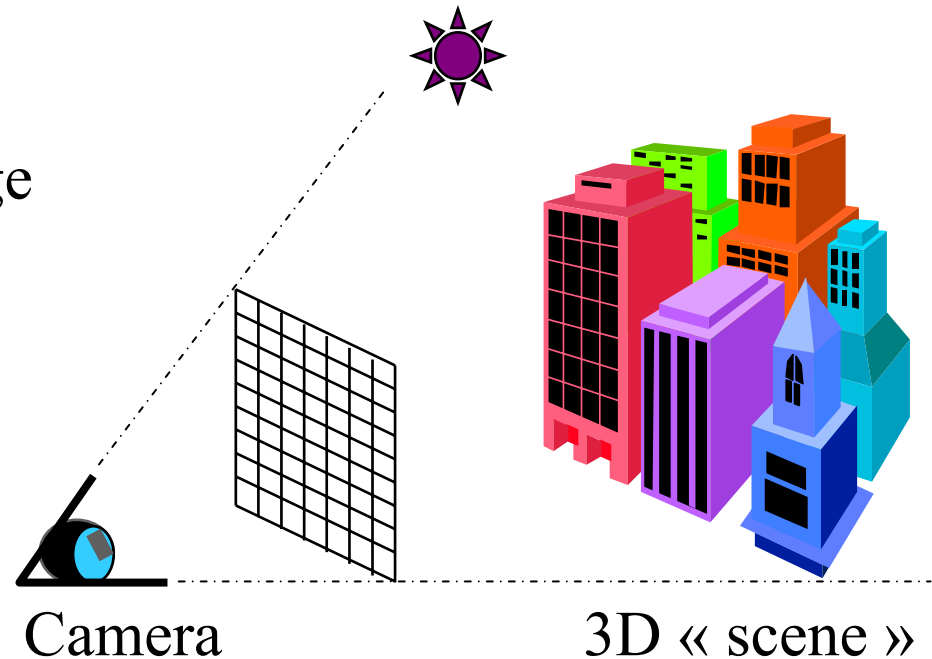
From a 3D scene to a 2D image

- based on geometry

Local illumination

Which color in each pixel?

- based on optics



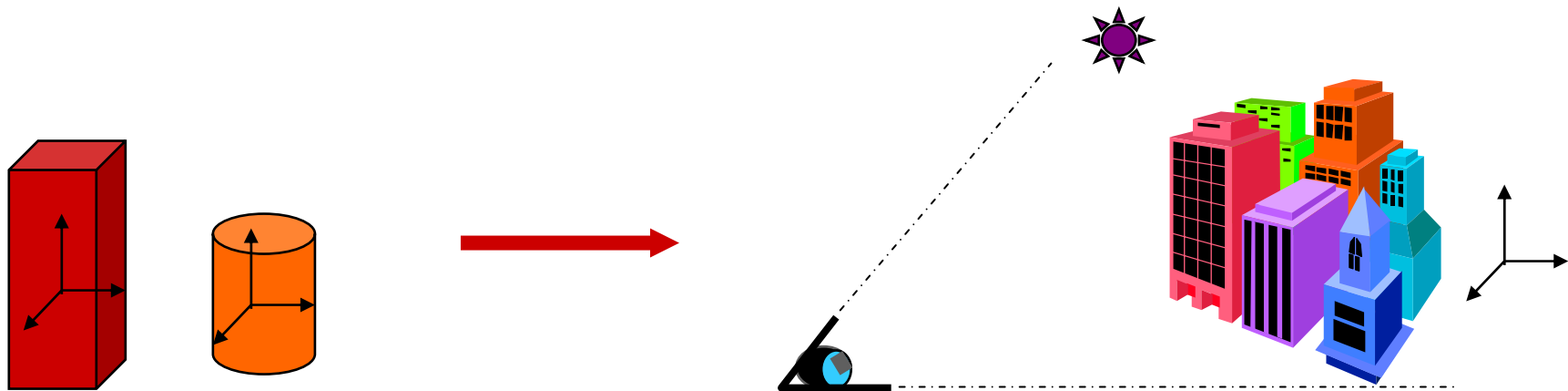
Graphics pipe-line

1. Create 3D models

- in local frames, faces = vertices + normals

2. Build the scene

- place instances of models in the “world frame”
- add materials, virtual lights, and a camera



Representation of transformations

- From frame to frame (rotate, translate, scale)?
 - Transformations represented by 4x4 matrices

$$\begin{pmatrix} x' \\ y' \\ z' \\ w' \end{pmatrix} = \begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$

$$p' = M p$$

Why 4x4? *Homogeneous coordinates*

- w will be used for projective transformations
- Cartesian coordinates: $w = 1$
- From projective to cartesian: divide by w

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} \quad \text{Affine transformation}$$

Affine transformations

Translation

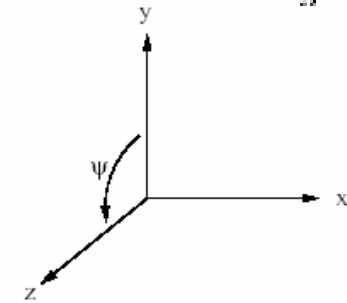
$$T = \begin{bmatrix} 1 & 0 & 0 & T_x \\ 0 & 1 & 0 & T_y \\ 0 & 0 & 1 & T_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Scale

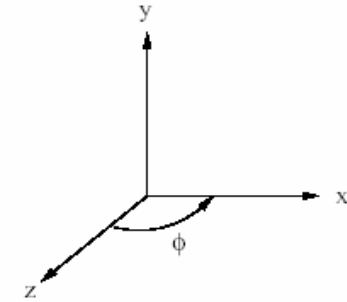
$$T = \begin{bmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Rotation: Euler angles $R = R_z \cdot R_y \cdot R_x$,

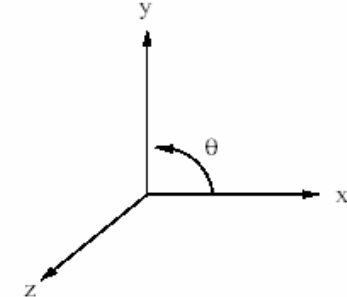
$$R_x = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \psi & -\sin \psi & 0 \\ 0 & \sin \psi & \cos \psi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



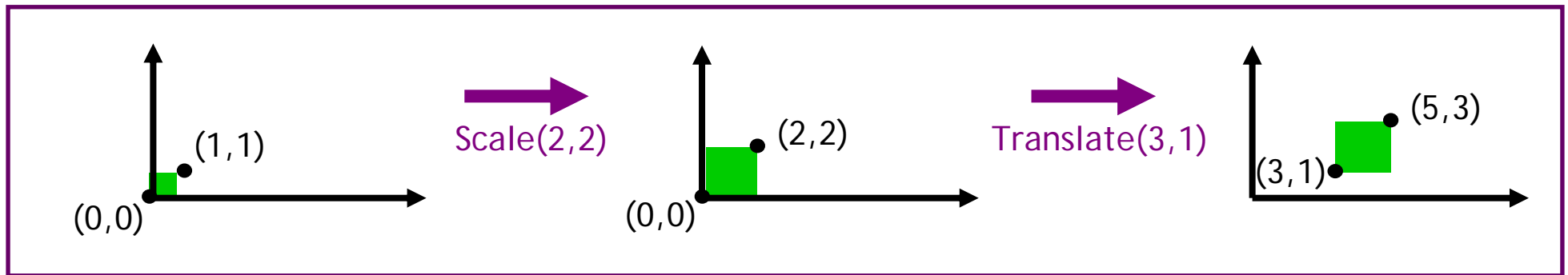
$$R_y = \begin{bmatrix} \cos \phi & 0 & \sin \phi & 0 \\ 0 & 1 & 0 & 0 \\ -\sin \phi & 0 & \cos \phi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$R_z = \begin{bmatrix} \cos \theta & -\sin \theta & 0 & 0 \\ \sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



Composition of transformations

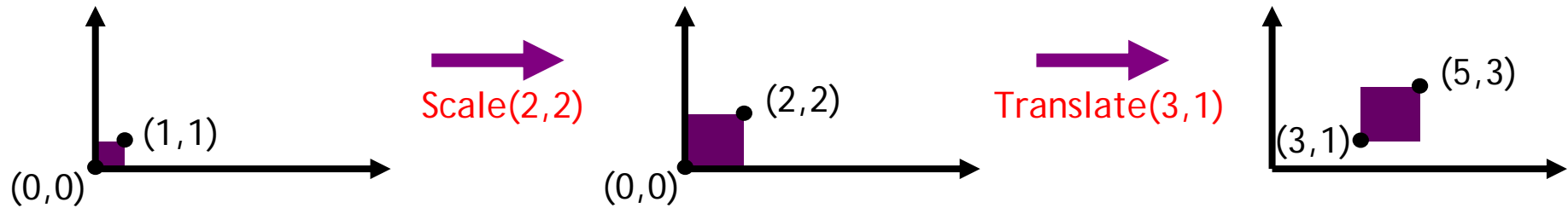


Multiplication of matrices : $p' = T (S p) = TS p$

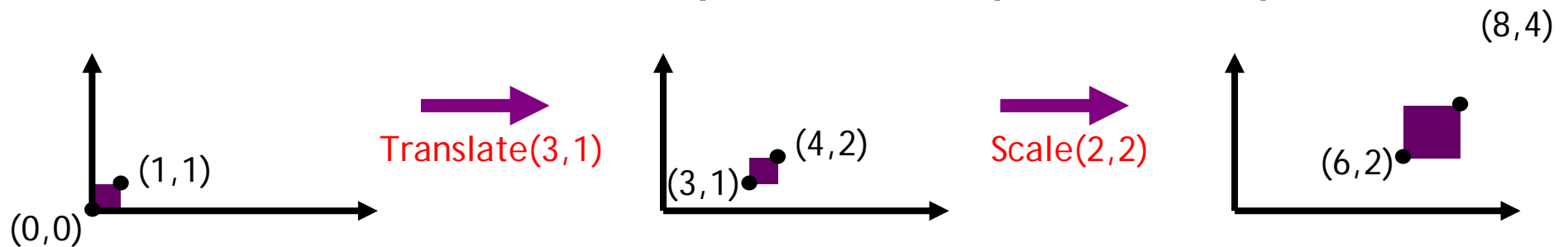
$$TS = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Not commutative !!!

Scale then translate : $p' = T (S p) = TS p$



Translate, then scale : $p' = S (T p) = ST p$

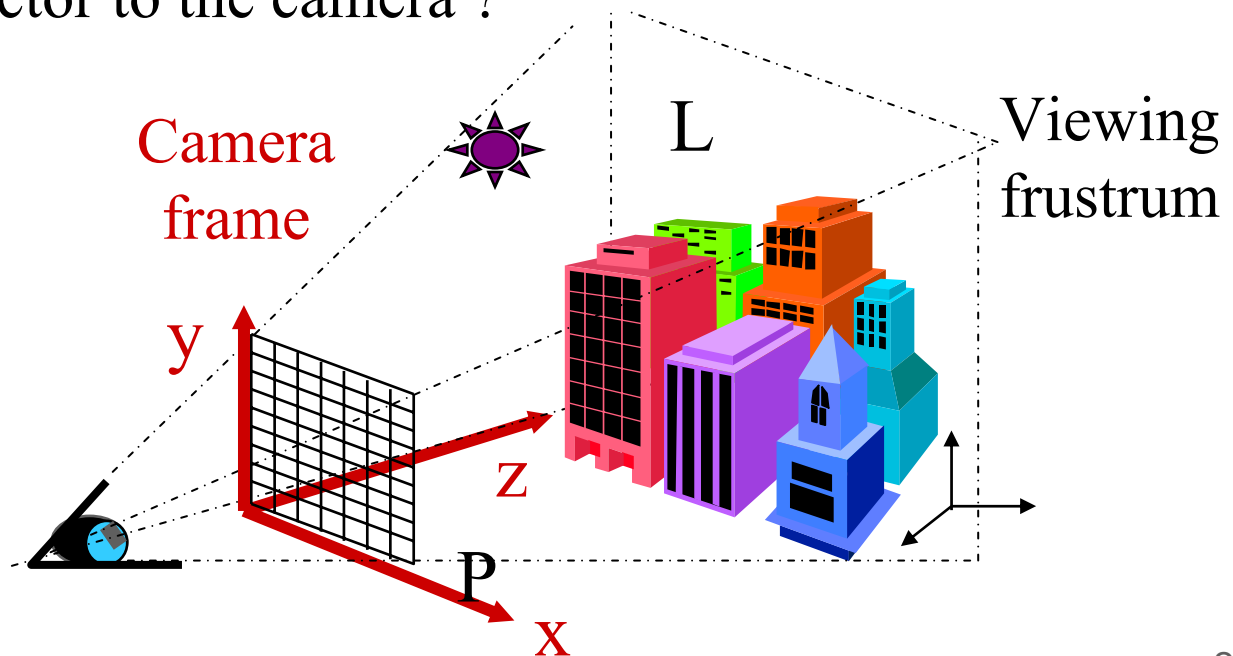


Graphics pipe-line

3. Convert the scene to the camera frame

- « cull » the faces that look in the opposite direction

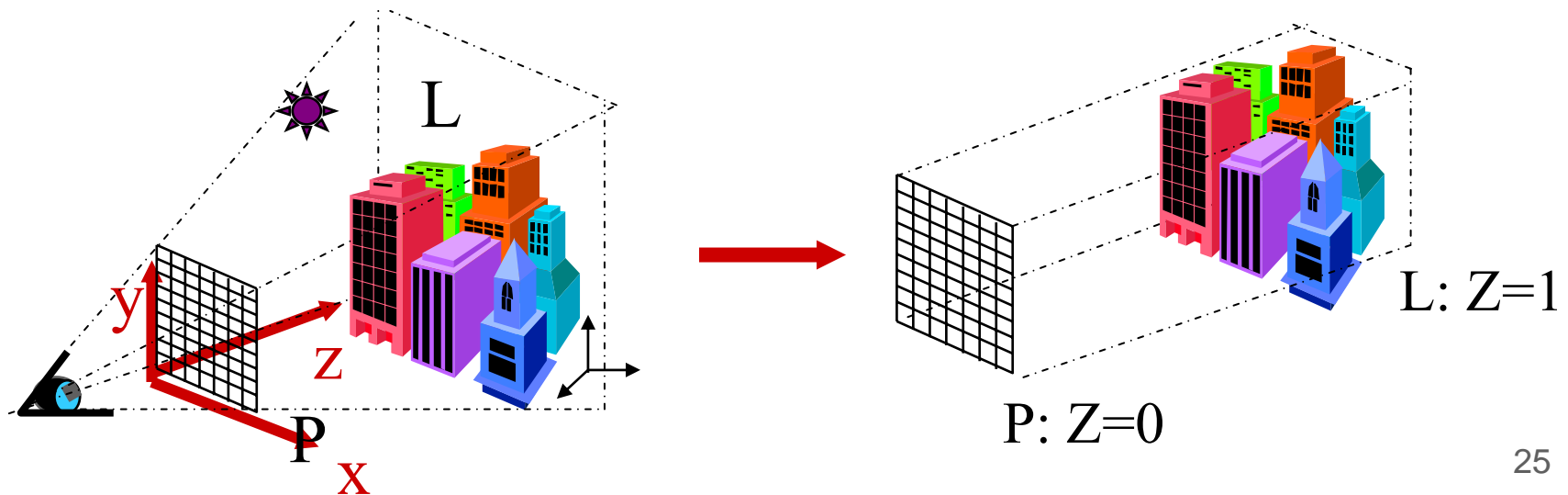
Normal \approx vector to the camera ?



Graphics pipe-line

4. Convert to the screen frame (**projective transformation!**)

- The viewing frustum becomes a parallelogram
- « clipping » operations to
 - suppress faces outside the frustum, cut intersecting ones



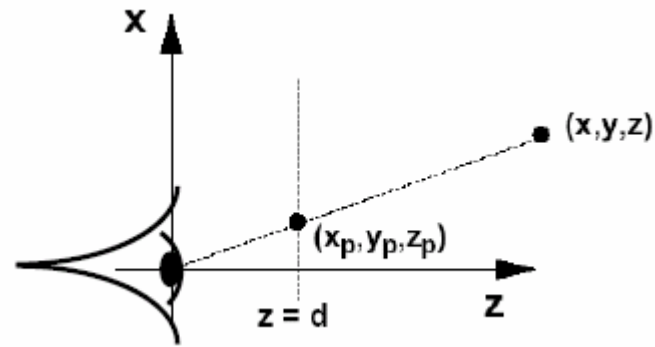
Perspective projection to image plane ?

- Project all points to the $z = d$ plane, eyepoint at the origin

$$x_p = \frac{d \cdot x}{z} = \frac{x}{z/d}$$

$$y_p = \frac{d \cdot y}{z} = \frac{y}{z/d}$$

$$z_p = d$$



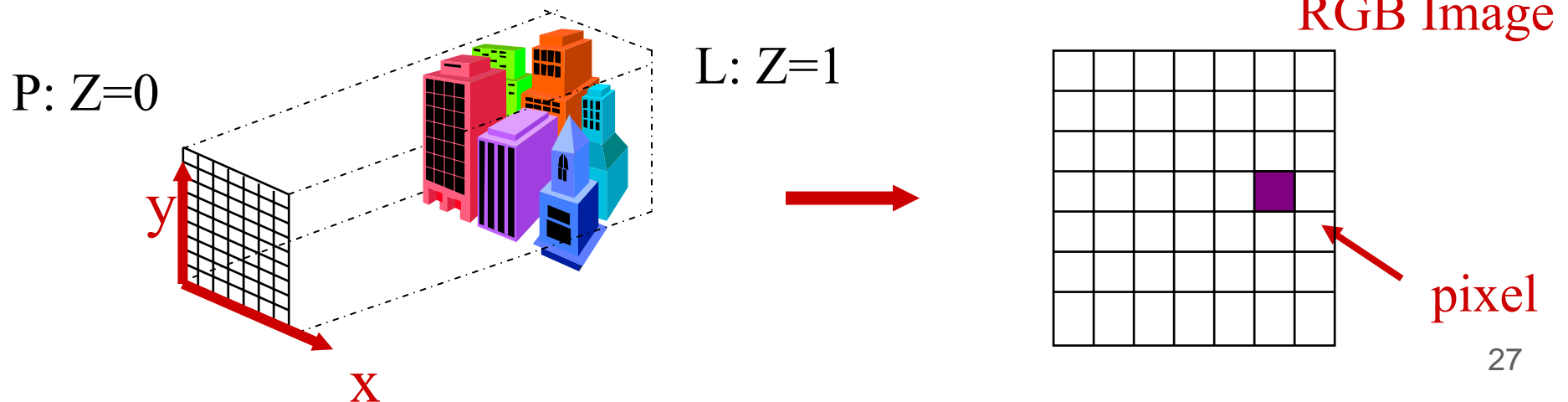
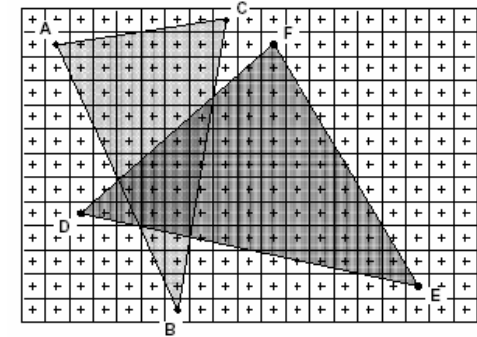
homogenize

$$\begin{pmatrix} x * d / z \\ y * d / z \\ d \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \\ z / d \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

Graphics pipe-line

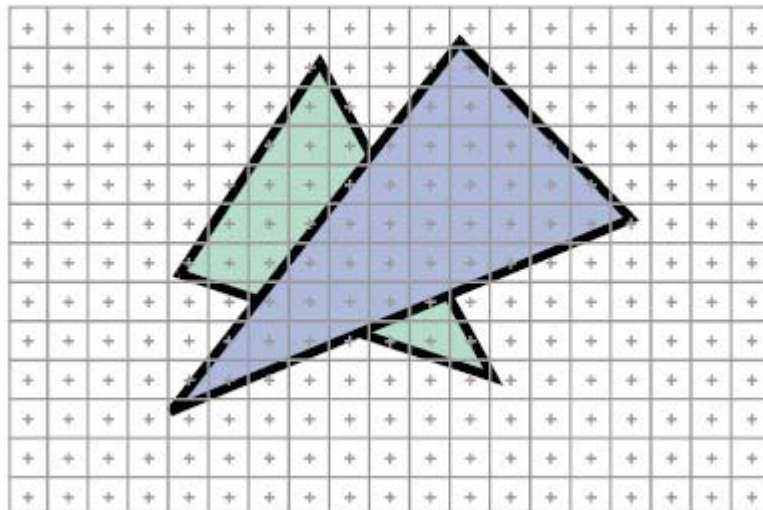
5. Compute the image

- Rasterize each face into pixels (x,y)
- Suppress hidden parts
- Compute a color for each pixel



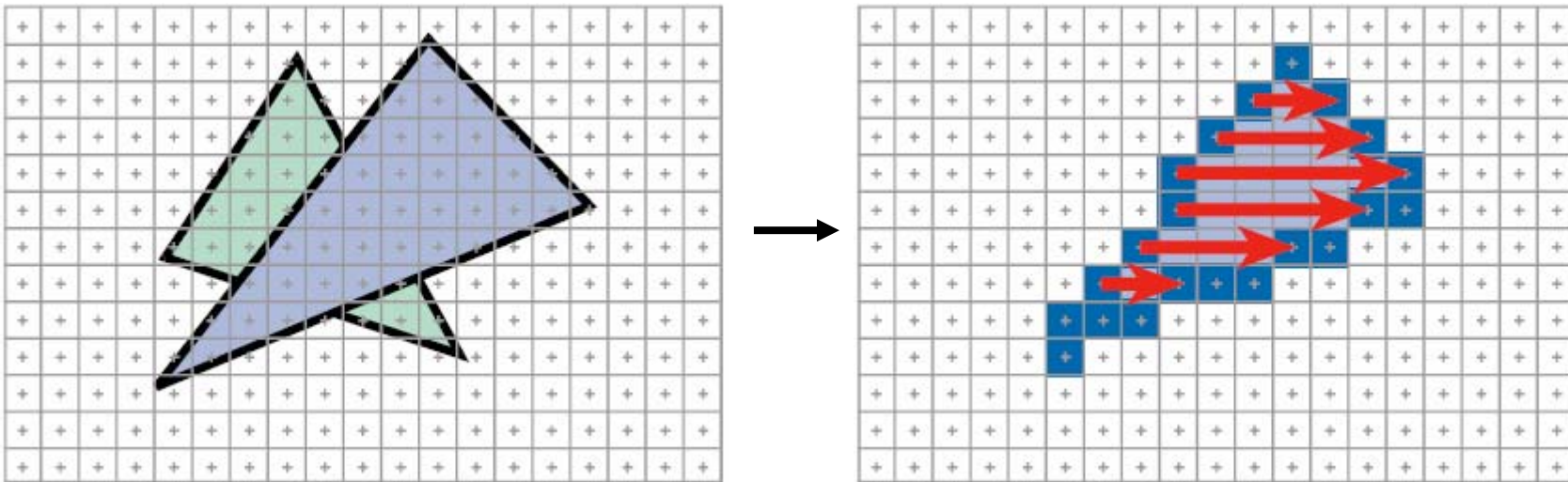
Rasterize faces into pixels?

- Primitives are continuous; screen is discrete
 - triangles are described by a discrete set of vertices
 - but they describe a continuous area on screen



Rasterize faces into pixels?

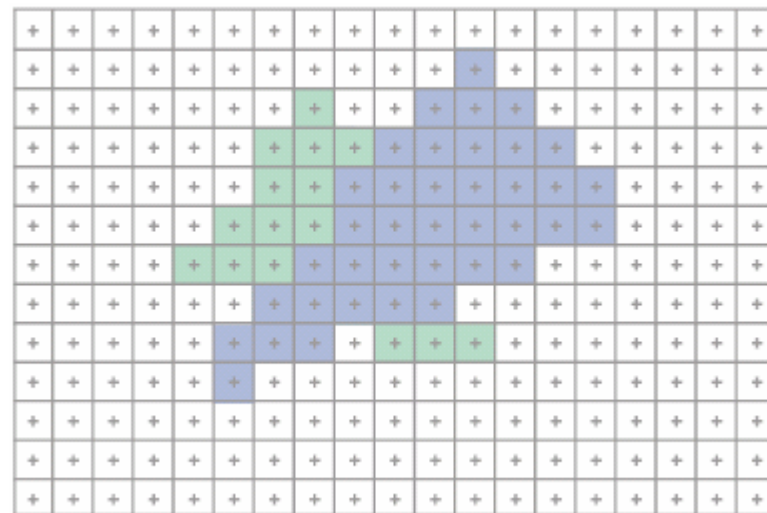
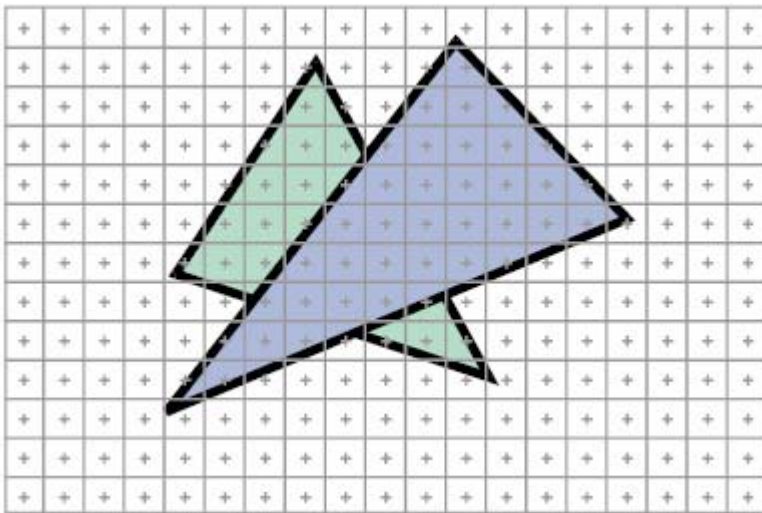
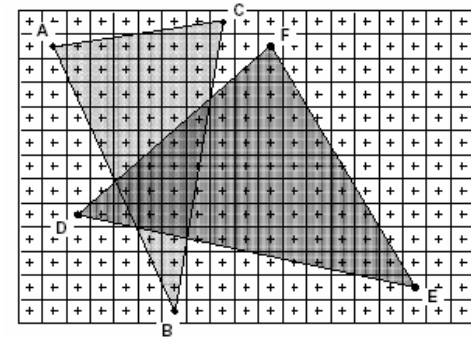
- Scan Conversion: approximation into pixels
 - Check pixels in BB wrt the 3 line equations
 - Scanline rasterization: increment from corner vertices



Graphics pipeline

Remove the hidden parts of each triangle?

Else the last one will appear « above »

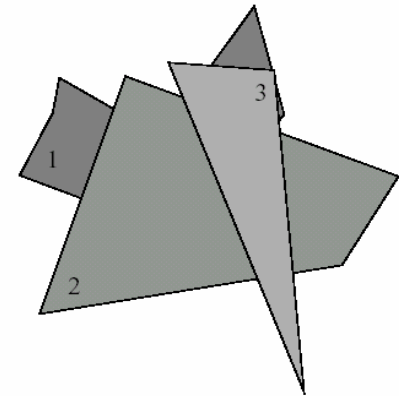


Graphics pipeline

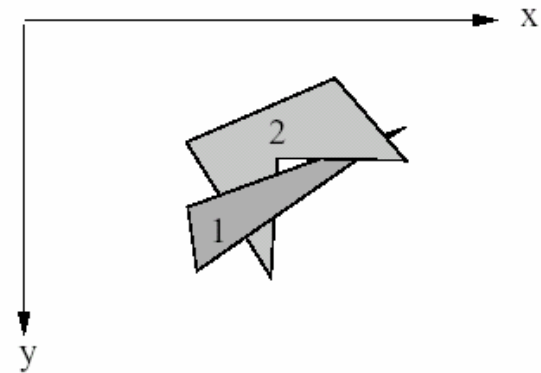
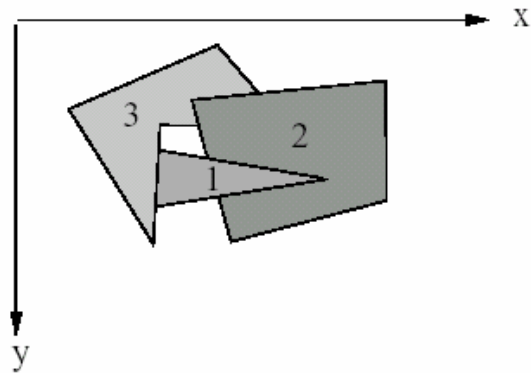
Remove hidden parts of each triangle?

– First method: the painter's algorithm

- Sort the faces
- Display triangles starting with the farthest



- Cost $n(\log n)$
- Problems!



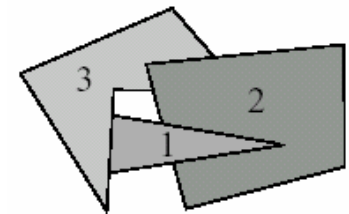
Graphics pipeline

Remove hidden parts?

- Use a « Z-buffer » (available thanks to memory)
 - A second array, as large as the image
 - Stores the current z value at each pixel
(the associated color being in the image buffer)

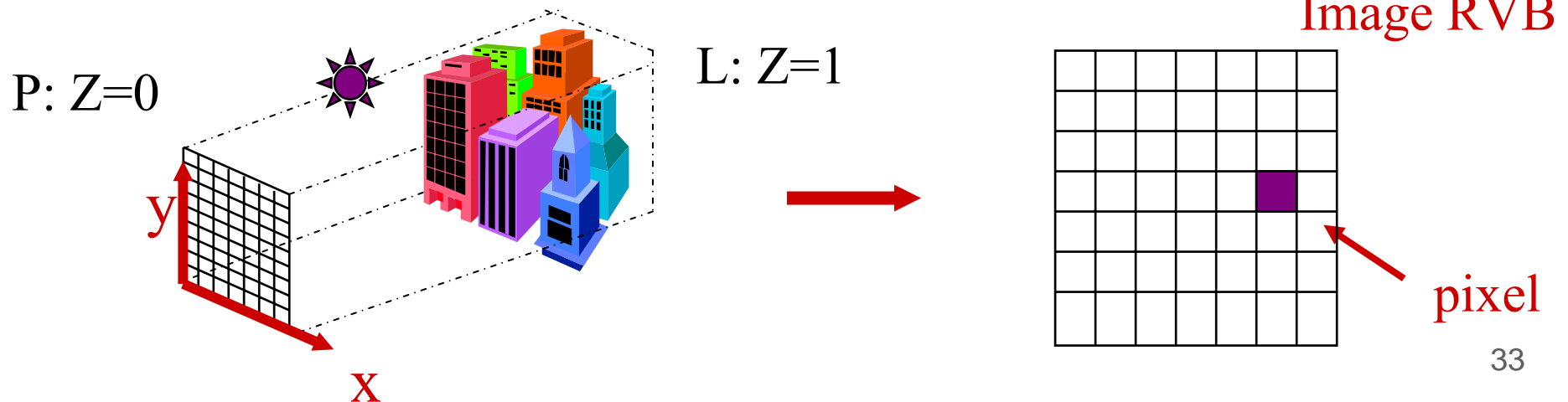
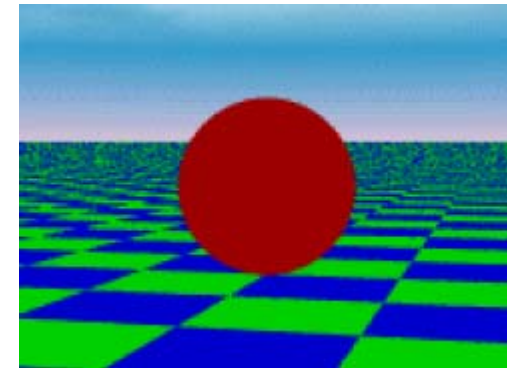
Algo

- Init with all pixel at max distance
- For each face, for each pixel P
 - update color and z-value iff ($z < \text{current z-value}(P)$)



Graphics pipeline

- Which color should be displayed?
 - Uniform colors would not work!
 - Given by a « local illumination » model



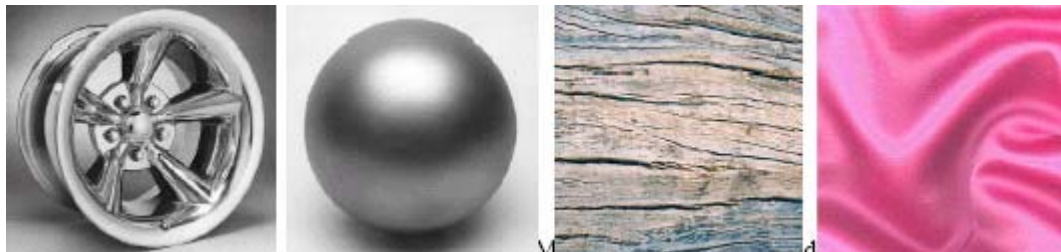
Local illumination

Which color shall we display in each pixel ?

⇒ Depends on the local amount of light coming back to the eyes

⇒ So it depends on :

- where the surface element is in 3D
- its orientation w.r.t. lights & camera
- the material the surface is made of

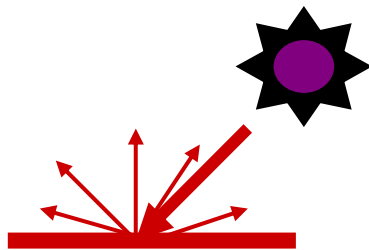


Phong's local illumination

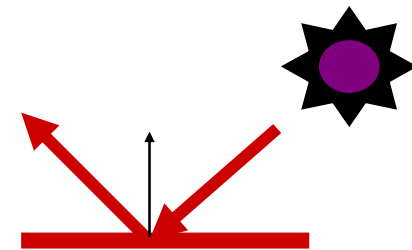
- A constant « ambient » term
- Direct lighting from the sources
 - no shadows
- Opaque objects only



diffuse



specular



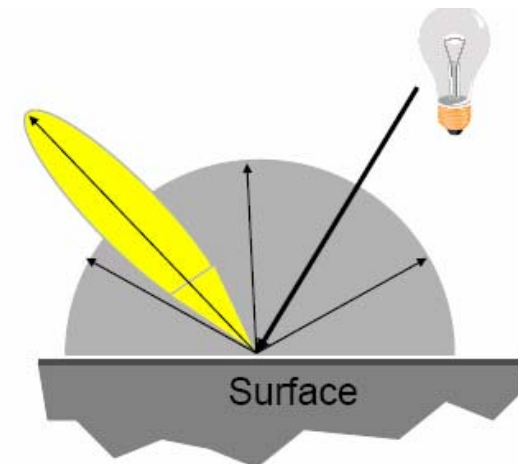
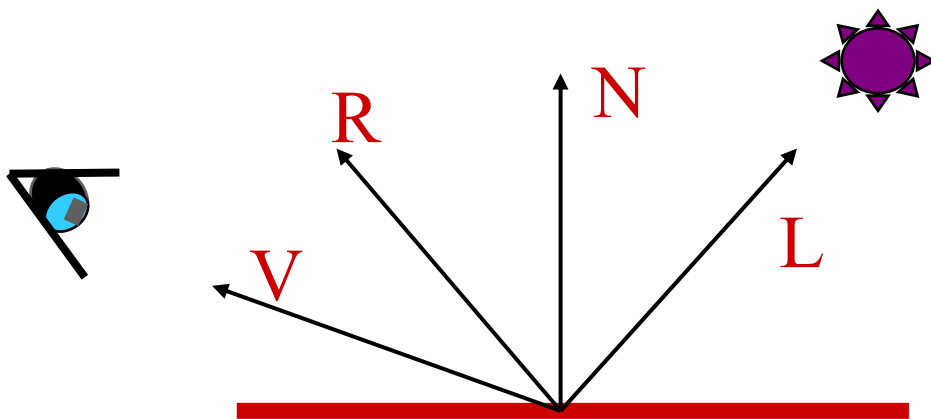
Phong's local illumination

$$I = K_a + \sum I_s (K_d L \cdot N + K_s (R \cdot V)^n)$$

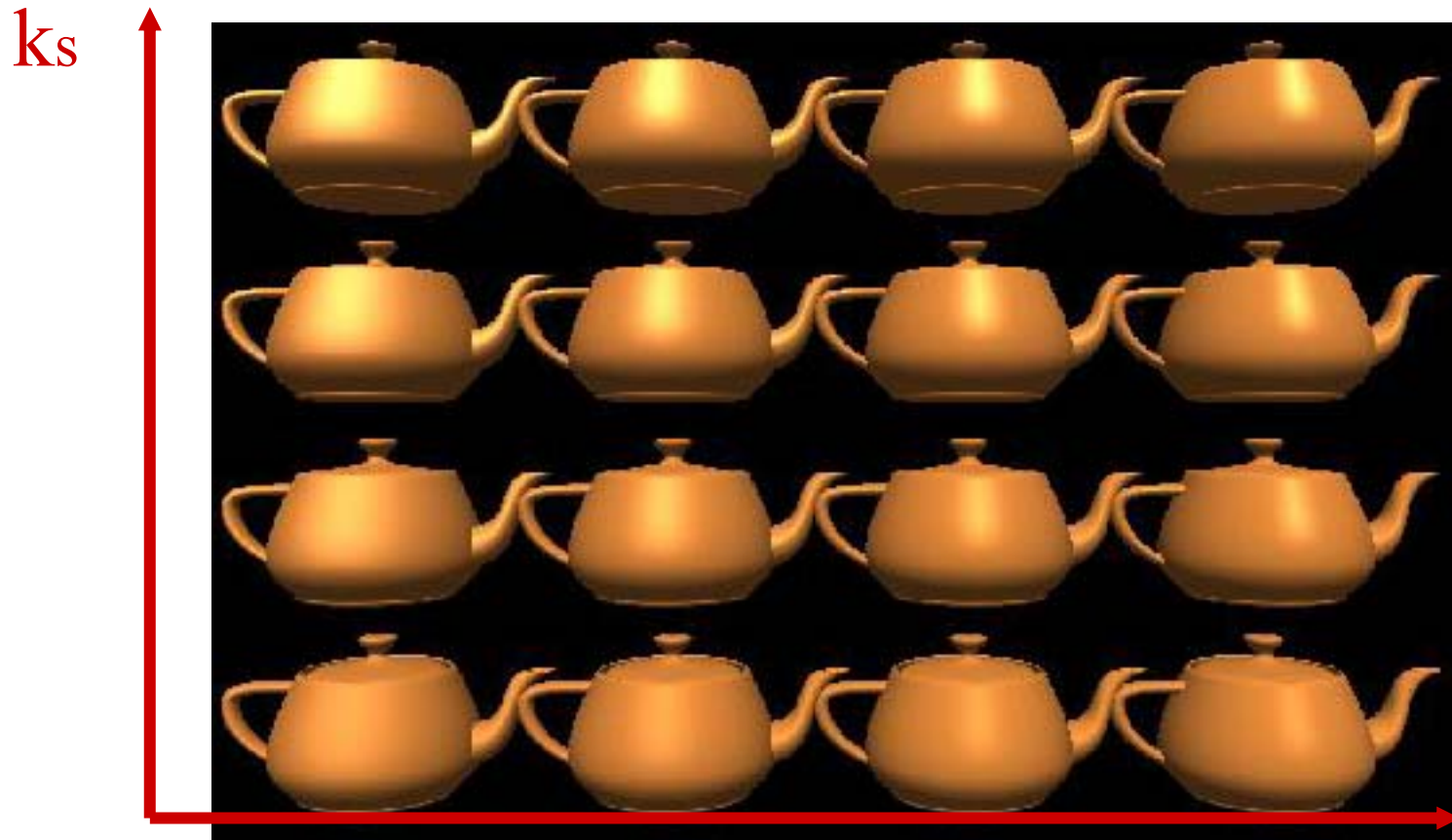
ambient

diffuse

specular

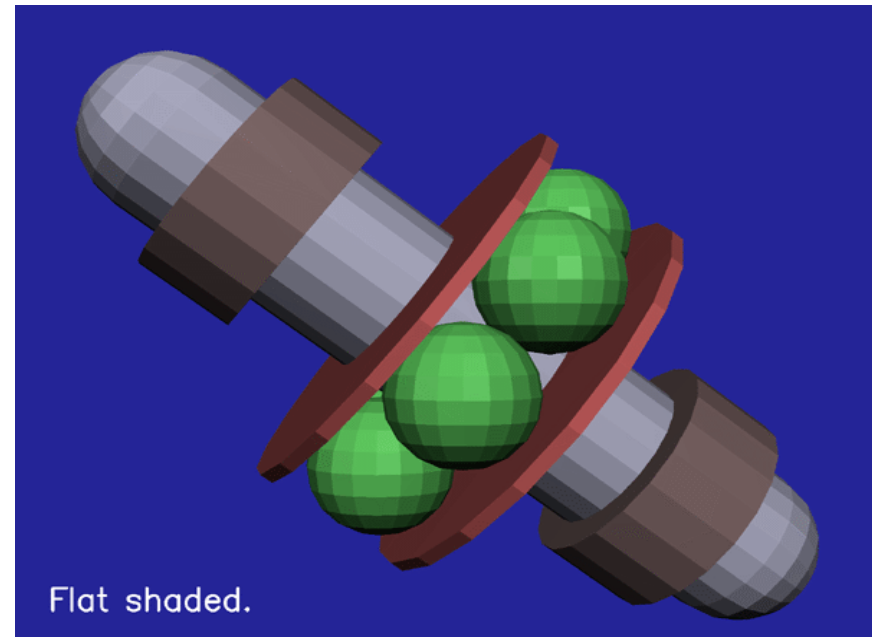


Phong's local illumination



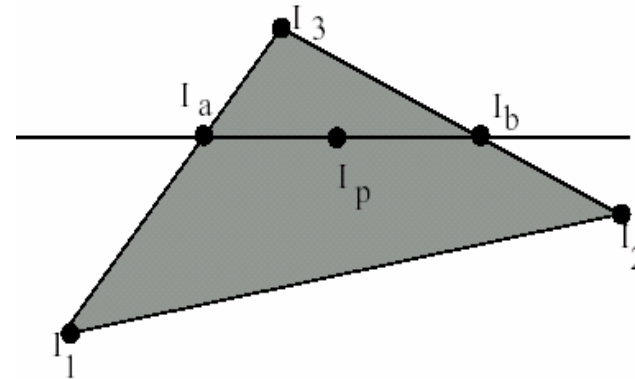
Direct application

- A single normal by face
- Uniform colors!



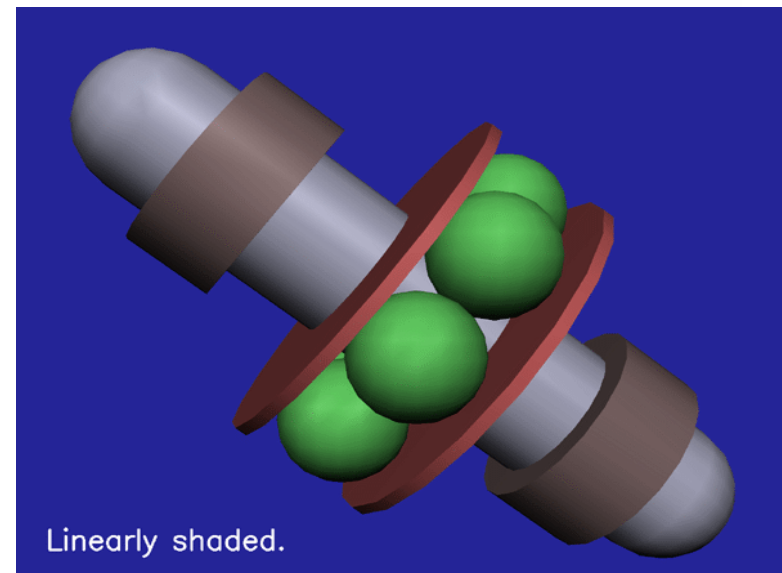
Gouraud's shading

- A normal by face
- Illumination on each vertex
- Bi-linear interpolation



Better!

Some reflexions can be missed



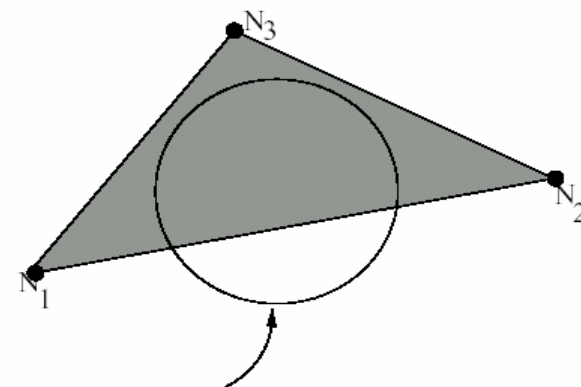
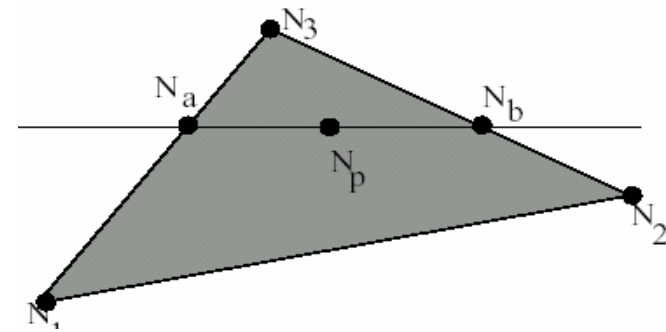
Phong's shading

- A normal by vertex
- Interpolate normal directions
- Illumination at each pixel

Correct!

Still missing:

- Cast shadows
- Extended light sources
- Transparency



Specular reflexion

Phong's shading

